



Effective: December 1996

Supersedes I.L. 41-496.52C, Dated January 1987

( ) Denotes Changed Since Previous Issue

## Type SDG-1T, -2T, -4T Static Ground Distance



**Before putting relays into service, remove all blocking which may have been inserted for the purpose of securing the parts during shipment, make sure that all moving parts operate freely, inspect the contacts to see that they are clean and close properly, and operate the relay to check the settings and electrical connections.**

### 1. APPLICATION

Type SDG-1T, 2T and 4T relays are single zone ground distance relays used to detect faults on sub-transmission or transmission lines. Table I shows the particular application intended for each relay and the components included.

The  $I_0$  fault detector prevents potential circuit trouble from causing immediate trip. The frequency verifier should be utilized for all high speed trip applications to avoid tripping on line energization or other conditions that cause high frequency transients.

The phase-to-phase desensitizer is used to eliminate a possible overreach on two-line-to-ground faults. This circuit is needed for Zone1 applications. It is not needed for overreaching applications. The nature of

Table 1

Relay	$I_0$ Fault Det	Freq. Verifier	Phase-to- Phase Desensitizer (Note 1)	Application
SDG-1T	X	X	X	Zone-1 or Zone-2
SDG-2T	—	X	X	Zone-1 or Zone-2
SDG-4T	—	—	—	Blocking Carrier Start

Note 1: For time delayed trip disconnect 2Ø-G circuit. A switch is provided for this function in the SDG-1T.

the design is that the phase-to-phase desensitizer is removed from service on settings  $S = 2$  or  $S = 3$ .

The potential supply must be 4 wire Wye-grounded. The broken delta voltage connection is provided inside the relay.

Mutual compensation is not required with these relays. With an 85% Zone1 setting and an extreme zero-sequence mutual impedance, the relay will reliably reach ground faults on at least 70% of the protected line.

All three relays are equipped with normally open output contacts and ICS's for indicating trip coil current flow. In addition the SDG-4T has a normally-closed contact for "contact-opening-carrier start".

*All possible contingencies which may arise during installation, operation or maintenance, and all details and variations of this equipment do not purport to be covered by these instructions. If further information is desired by purchaser regarding this particular installation, operation or maintenance of this equipment, the local ABB Power T&D Company Inc. representative should be contacted.*

### 1.1. Fundamentals of Distance Measurement On Ground Faults

The SDG-T type distance relay operates on both single and double line-to-ground faults. In either case, neglecting fault resistance, the faulted phase-to-ground voltages at the relay consists of the line drop:

$$\begin{aligned} V_{LG} &= \text{Faulted phase-to-ground relay voltage} \\ &= K_1 I_1 nZ_{1L} + K_2 I_2 nZ_{1L} + K_0 I_0 nZ_{0L} + \\ &\quad I_{0E} nZ_{0M} \end{aligned} \quad \text{Eq. (1)}$$

Where  $K_1$ ,  $K_2$ ,  $K_0$  are current distribution factors for the pos., neg., and zero sequence networks, respectively.

$I_1$ ,  $I_2$ ,  $I_0$  are the pos., neg., and zero sequence currents **in the fault**.

$nZ_{1L}$ ,  $nZ_{0L}$  are the pos. and zero sequence line impedances **to the fault**.

$I_{0E}$  is the adjacent line zero sequence current.

$Z_{0M}$  zero sequence mutual impedance.

See Figure 16 for further definition of terms. For an A to ground fault Eq. ( 1 ) would be written in terms of the phase A quantities (ignoring mutual effect).

$$V_{AG} = K_1 I_{A1} nZ_{1L} + K_2 I_{A2} nZ_{1L} + K_0 I_0 nZ_{0L} \quad \text{Eq. (2)}$$

Eq. ( 2 ) also applies for an AB to ground fault or any other fault. Additional expressions apply for the phase B and C quantities.

A distance ground relay made to respond to single phase-to-ground faults will also respond in the same way to double line-to-ground faults. This is true except for the effect of ground resistance,  $R_G$ . The different nature of these effects can be sensed from Figure 17. In Figure 17 the ground current  $3I_0$  flowing through  $R_G$  is essentially in phase with the total faulted phase current. This is so, since  $I_{A1} = I_{A2} = I_0$ . This is not true for a 2L-G fault. The current  $3I_0$  is out of phase with  $K_1 I_{A1}$  and  $K_2 I_{A2}$  (also out of phase with  $K_1 I_{B1}$  and  $K_2 I_{B2}$ ). As a result the drop across  $R_G$  produces an apparent reactance term to the distance relay, causing it to underreach on one phase and

overreach on the other faulted phase. The SDG-1T and SDG-2T relays contain a desensitizer circuit to prevent overreach on 2L-G faults, by reducing the reach of the relay.

The restraint voltages  $V_{XN}$ ,  $V_{YN}$ ,  $V_{ZN}$  are obtained by the use of compensators with an impedance  $Z_C$ , set to match the desired positive sequence line impedance reach. Only positive and negative sequence voltages appear in Eq. ( 3 ) to ( 5 ).

$$V_{XN} = (V_{A1} + V_{A2}) - Z_C (K_1 I_{A1} + K_2 I_{A2}) \quad \text{Eq. (3)}$$

$$V_{YN} = (V_{B1} + V_{B2}) - Z_C (K_1 I_{B1} + K_2 I_{B2}) \quad \text{Eq. (4)}$$

$$V_{ZN} = (V_{C1} + V_{C2}) - Z_C (K_L I_{C1} + K_2 I_{C2}) \quad \text{Eq. (5)}$$

The zero sequence voltage is filtered out by not grounding the neutral of the set of Y-connected auxiliary transformers ( $T_{A2}$ ,  $T_{B2}$  and  $T_{C2}$ ) which are used to feed the restraint portion of the magnitude comparison circuit. These same connections render the zero sequence current flowing in the phase compensators ineffective. So the restraint voltages duplicate the delta voltage conditions at the fault when the fault is  $Z_C$  ohms from the relay (i.e., at the balance point). Zero sequence quantities are not required to duplicate the system voltage triangle at the balance point since zero sequence voltages cancels out of the line to line voltages.

The operating voltage is:

$$V_{WO} = V_0 - \frac{Z_{0L}}{Z_{1L}} \mp Z_C \left( K_0 I_0 + I_{0E} \frac{Z_{0M}}{Z_{0L}} \right) \quad \text{Eq. (6)}$$

Here  $V_0$  is the relay zero sequence voltage: it is compensated by using a compensator impedance ( $Z_{0L}/Z_{1L}$ )  $Z_C$  representing the zero sequence line impedance to the desired balance point. For mutual coupled lines this compensator can be fed with not only the protected line current but also with a portion of the mutual current  $I_{0E}$  (See Figure 16). The operat-

ing voltage  $V_{WO}$  duplicates the system zero sequence voltage for fault at the balance point.

Since the faulted phase-to-ground voltage is zero at the fault (neglecting fault resistance), the operating and faulted phase restraint voltage will be equal for a balance point fault. This can be seen by manipulating the fault voltage expression, remembering that the relay compensated voltages are a replica of the fault-point voltages:

$V_{LGF}$  = Faulted phase-to-ground voltage at the fault

$$= V_{1F} + V_{2F} + V_{0F} = 0 \quad \text{Eq. (7)}$$

$$V_{1F} + V_{2F} = -V_{0F} \quad \text{Eq. (8)}$$

$$|V_{1F} + V_{2F}| = |V_{0F}| \quad \text{Eq. (9)}$$

Eq. (9) states that the magnitude of the sum of the pos. and neg. sequence voltage equals the magnitude of the zero sequence voltage at the fault. This holds regardless of how many phases are grounded. Eq. (9) is the keystone of the SDG system.

This balance point condition is shown in Figure 18 for an A-G fault. The bus voltages ( $V_{A1} + V_{A2}$ ) and  $V_0$  are shown along with the compensator voltages, which modify the bus voltages to produce restraint voltage  $V_{XN}$  and operating voltage  $V_{WO}$ .

For this condition  $V_{YN}$  and  $V_{ZN}$  are also produced but these will be larger in magnitude since these are derived from the sound phases. Since these voltages exceed  $V_{XN}$ , they are irrelevant.

In Figure 18 for a fault beyond the balance point,  $V_{XN}$  exceeds  $V_{WO}$ ; the reverse is true for the fault within the balance point. Note that for all these faults in the trip direction that the phase compensation acts to reduce the bus positive and negative sequence voltages; whereas, the zero sequence compensation is added to  $V_0$ . The reverse is true for a fault behind the relay. For this reason the SDGT is inherently directional as long as relay is set for no more than 1.5 times the impedance of the protected line, when operating voltage exceeds unfaulted phase restraints.

One other aspect of Figure 18 bears amplification. Note for the fault within the balance point that the phase compensation is almost enough to reverse

$V_{XN}$  polarity. It is possible for such a reversal to occur, and it is possible if very little zero sequence flows for the phase compensation to overtake the operating voltage and restrain the relay. Thus, the relay may fail to see a close-in fault if the zero sequence current is quite small. Any time this extreme condition occurs the phase-distance relay will operate. The phase-distance relay will clear the fault when:

$$Z_1 > \frac{V_0 \S I_0}{K_1 + K_2 + pK_0}$$

where  $Z_1$  is positive sequence relay reach

$V_0$  = zero sequence bus voltage for close-in fault

$I_0$  = total zero sequence fault current for close-in fault

$K_1, K_2, K_0$  pos.-, neg.- and zero sequence current distribution factors for close-in fault

$p$  = ratio of zero sequence to positive sequence line impedance

## 2. CONSTRUCTION AND OPERATION

The type SDGT relay consists of: four air gap transformers, three auto-transformers for reach adjustment, four phase-splitter transformers, one isolating transformer which couples the zero sequence network ac output to the static frequency verifier circuit, one zero sequence current-to-voltage transformer, four phase-splitter and rectifier networks, a double line-to-ground fault desensitizer, one voltage regulating Zener diode, a telephone relay for the output function and printed circuit assemblies. The indicator contactor switch provides trip indicator and seal-in for the telephone relay contact.

The large printed circuit assembly contains a magnitude comparator, frequency check circuit, and the zero sequence current detector.

### 2.1. Compensators ( $T_A, T_B, T_C, T_O$ )

The compensators (Figure 13), which are designated  $T_A, T_B, T_C$ , and  $T_O$  are two-winding air gap transformers. Each current winding has seven taps which terminate at the tap block. A voltage is induced in the secondary which is proportional to the primary tap and current magnitude. This proportionality is established by the cross sectional area of the laminated steel core, the length of an air gap which is located in

the center of the coil, and the tightness of the laminations. All of these factors which influence the secondary voltage have been precisely set at the factory. The clamps which hold the lamination should not be disturbed by either tightening or loosening the clamp screws.

The secondary winding has a single tap which divides the winding into two sections. One section is connected subtractively in series with the relay terminal voltage. Thus a voltage which is proportional to the phase current is subtracted vectorially from the relay terminal voltage. The second section is connected to an adjustable loading resistor (R1, R2, R3, R4) and provides a means of adjusting the phase angle between primary current and the induced secondary voltage. The phase angle may be set for any value between 60° and 90° by adjusting this resistor. The factory setting is for a maximum sensitivity angle of 75° current lagging voltage.

A tertiary winding M has four taps which may be connected to directly modify the T setting by any value from -18 to +18 percent in steps of 3%. The sign of M is negative when the R lead is above the L lead. M is positive when L is in a tap location which is above the tap location of the R lead. The M setting is determined by the sum of per unit values between the R and L lead. The actual per unit values which appear on the tap plate between taps are 0,.03,.09 and .06.

## 2.2. Auto-Transformer ( $T_{A1}$ , $T_{B1}$ , $T_{C1}$ )

The auto-transformers  $T_{A1}$ ,  $T_{B1}$ ,  $T_{C1}$  have three taps on their main winding S which are numbered 1, 2 and 3 on the tap block.

The three secondary windings of the auto-transformers are connected in a "broken delta", thus serving as a source of zero sequence voltage for the operating circuit. The primary to secondary turn ratio is 3 : 1, thus producing the proper zero sequence voltage magnitude as required by the theory of relay operation. Using S = 2 or S = 3 settings reduces zero sequence voltage in the same proportion as the line-to-neutral voltages.

The auto-transformer makes it possible to expand the basic range of T ohms by a multiplier of S.

## 2.3. Phase-Splitter Transformer ( $T_{A2}$ , $T_{B2}$ , $T_{C2}$ , $T_{O2}$ )

The phase-splitter transformer provides isolation between the ac analog network and the magnitude comparator circuitry located on the printed circuit board, and couples the restraint and operating out-

puts to the phase-splitter network. The tap connection on the secondary winding serves as part of the phase-splitting circuit that converts a single-phase input into a three-phase output, thus minimizing the ripple of the rectified output.

## 2.4. Isolating Transformer ( $I_O$ )

The isolating transformer  $I_O$  serves two purposes: First it isolates the ac circuit from the dc circuit, and second, it produces a secondary voltage in the presence of zero sequence current.

## 2.5. Isolating Transformer ( $T_{FV}$ )

The isolating transformer  $T_{FV}$  serves two purposes: First, it isolates the ac circuit from the dc circuit and second, it steps up the clipped ac signal to make the frequency check circuit sensitive to low level input signals.

## 2.6. Double Line-to-Ground Fault Desensitizer

The double line-to-ground fault desensitizer consists of the three networks. Each network consists of a resistor and a minimum voltage network. In this network the largest restraint voltage is blocked by a combination of two restraining voltages. If any two restraining voltages become smaller than the third restraint voltage, transistors Q17 and Q18 are turned on to prevent Q1 transistor from turning on. When operating voltage becomes larger than the highest restraint the relay is allowed to trip.

### 2.6.1. For SDG-T

A two phase-to-ground switch is connected between pin 8 of the 2Ø-Gnd. Circuit board S-203C369G01 and the positive supply bus. This permits de-activation of the 2Ø-Gnd. circuit when desired by opening the switch.

The desensitizer effect is limited to S = 1 setting only and is not effective on the S = 2 or S = 3 setting. If S = 2 or S = 3 setting is used for Zone1 the setting should be reduced to 75% of the protected line to avoid overreach on double line-to-ground faults. For SDG-2T unsolder pin 8 connection to disable the circuit.

## 2.7. Magnitude Comparator Circuit

The magnitude comparator circuit consists of a minimum voltage network of the voltage balance type in which operating current is caused to flow through a current detector whenever one of the phase restraint voltages becomes smaller than the operating voltage.

Resistors (R9, R10, R11), shown in Figure 5, provide a return path for the operating current.

The sharp turn-on characteristic is obtained by use of special voltage reference circuit that consists of R33, R34, R35 and TH2 (for temperature compensation). The TP2 potential derived from this reference circuit provides base drive for Q8 transistor that is prevented from turning on as long as Q2 is turned on by TP1 potential. Whenever operating voltage  $V_{WO}$  exceeds one of the restraint voltage ( $V_{XN}$ ,  $V_{YN}$  or  $V_{ZN}$ ) transistor Q1 is turned on lowering the TP1 potential below TP2 potential thus making it possible for Q8 to conduct, thus turning on Q9 and after time delay controlled by R45-C9 time constant (or R76-C9 for SDG-1T, -2T or R77-C9 for SDG-4T relays), producing an output.

## **2.8. Zero Sequence Current Detector (SDG-1T Only)**

To prevent operation of the magnitude comparator during a blown potential fuse or unequal pole closing, a zero sequence current detector supervises the operation of the triggering network by preventing capacitor C10 in the triggering circuit from charging, keeping the input to D51 at low potential through the diode D59.

With no or very low zero sequence current Q12 transistor is conducting.

In the presence of the residual current a current derived negative voltage through transformer  $I_0$  appears across resistor R60, turns transistor Q12 off and thus raising its collector close to the positive dc voltage supply level, blocking D59 from discharging the C10 capacitor allowing Q13 to operate.

## **2.9. Frequency Verification**

During certain switching conditions, such as energization of a transmission line, residual currents and voltages may exist of higher frequencies than 60 hertz per second. The frequency verifier prevents relay operation when the operating voltage period is less than 5 ms. The frequency verification circuit consists of two functional parts: zero-crossing and timing circuit. The zero-crossing circuit consists of transistors Q3, Q4, Q5 and Q6. The zero-crossing circuit is used to allow operation in the presence of higher frequencies of small magnitude superimposed on a fundamental of 60 Hz. During the positive or negative half cycles of the operating voltage  $V_{WO}$ , Q3 or Q4 transistors are driven into saturation by the output of the  $T_{FV}$  transformer. Transistor Q5 conducts until

capacitors C6 or C7 respectively are fully charged. While either capacitor is charging through R29, transistor Q5 drives transistor Q6 to discharge timing capacitor C9, thus starting the timing cycle with close to zero charge on the capacitor. The function of the timing capacitor is to delay the operation of the relay for 5 milliseconds. The delay is obtained by delaying the firing time of Z2 Zener diode. If a next zero-crossing should occur within the preset delay time, C9 capacitor is discharged again and the timing cycle is repeated. In case of presence of predominant higher frequencies (over 100-140 Hz), several zero-crossing pulses will occur within the preset time delay, thus keeping the C9 capacitor from charging up to the Zener firing voltage.

The transient blocking is accomplished through the operation of Q7 transistor that is driven by a short pulse formed through R46 and C8 capacitor to clear C9 capacitor of any charge before initiating 5 millisecond delay. Any tripping signal coming off Q9 transistor of a duration less than 5 milliseconds output circuit will not produce a relay output.

### **2.9.1. For SDG-1T and SDG-4T**

The coil of the telephone relay is in series with the collector of transistor Q16 so that, when Q16 is turned on, the telephone relay is energized causing the contacts to close. A Zener diode is connected across the collector of Q16 to limit the inductive kick voltage appearing at the collector during the pickup and dropout of the telephone relay.

### **2.9.2. For SDG-2T**

The coil of the telephone relay is in series with the collector of transistor Q14 so that, when Q14 is turned on, the telephone relay is energized causing the contacts to close. A silicon diode is connected across the coil of the telephone relay to limit the inductive kick voltage appearing at the collector during the pickup and dropout of the telephone relay.

## **2.10. Push-button Check Circuit**

### **2.10.1. SDG-2T Only**

For the SDG-2T relay the push-button check circuit is used for in-service operational check-out of the output relay is used on  $S = 1$  setting. Depressing the push-button operates the overcurrent circuit. This action must be preceded by the opening of the relay trip circuit (red handle) and relay voltage to neutral switch 7. The opening of the voltage switch produces operating voltage conditions in the magnitude comparator that gates the thyristor switch. Operation of

the relay switch is indicated by the lighting of the bulb built into the push-button.

### 3. CHARACTERISTICS

#### 3.1. Distance Characteristics

Figure 14 shows the relay characteristic in the complex plane is  $Z = nZ_{1L} + \frac{3R_G}{F}$  for single-line-to-ground faults where factor  $F = K_1 + K_2 + pK_0$ , where  $K_1$ ,  $K_2$ ,  $K_0$  are positive, negative and zero sequence current distribution factors and  $p$  = ratio of zero sequence to positive sequence line impedance. Impedance  $nZ_{1L}$  is the positive sequence line impedance from the relay to the fault. The apparent impedance  $Z$  must fall within the characteristic shown in Figure 14 in order to operate. The R-X characteristic is a composite of three circles whose centers are A, B, and C in Figure 14a. The circle whose center is "A" is produced from the comparison of faulted phase restraint and operating voltage for a single-line-to-ground fault; whereas the "B" and "C" circles result from sound-phase restraint comparison with operating voltage. Note that part (a) of Figure 14 applies for the case of a low source impedance vs. line impedance; parts (b) and (c) represent increasing amounts of source impedance, or conversely shorter line lengths. The solid-line characteristic is based on current distribution factors for a balance point fault with all breakers closed. As the fault moves toward the relay these distribution factors increase, with the relay approaching the dashed-line characteristic. In the case of Figure 14c, the dashed-line characteristic is not shown, as it essentially coincides with the solid line characteristic. Regardless of system conditions, the relay reaches  $Z_C$  positive sequence ohms for a fault at the compensator angle. The fact that the circle diameter expands with increasing source impedance is beneficial, since this provides increased fault resistance accommodation for the shorter line applications. By this we mean that it takes a

greater  $\frac{3R_G}{K_1 + K_2 + pK_0}$  component to yield a  $Z$

phasor which is outside the operate zone. In Figure 14c only the faulted phase characteristic is shown, since the other two fall well out of the first quadrant.

One might conclude from Figure 14 that the relay is not directional since its characteristic includes the origin. **This conclusion would be erroneous**, since the characteristic equations assume faults in the trip

direction per Figure 14 and do not apply for reversed faults. **The relay is directional.** In Figure 14 the second and third quadrants are essentially theoretical since a "negative resistance" is only possible due to out-of-phase infeed. The fourth quadrant is pertinent for series capacitor applications. So we are normally only interested in the first quadrant.

#### 3.2. General Characteristics

Impedance settings in ohms reach can be made in steps of 3 percent. The maximum sensitivity angle, which is set for 75 degrees at the factory, may be set for any value from 60 degrees to 82 degrees. A change in the maximum sensitivity angle will produce a slight change in reach for any given setting of the relay. Referring to Figure 13, note that the compensator secondary voltage output  $V$ , is largest when  $V$  leads the primary current,  $I$ , by 90°. This 90° relationship is approached, if the compensator loading resistor is open-circuited. The effect of the loading resistor, when connected, is to produce an internal drop in the compensator, which is out-of-phase with the induced voltage,  $IT_A$ ,  $IT_B$ , or  $IT_C$ . Thus the net voltage  $V$ , is phase-shifted to change the compensator maximum sensitivity angle. As a result of this phase shift the magnitude of  $V$  is reduced, as shown in Figure 13. The tap markings are based upon a 75° compensator angle setting. If the resistors  $R_1$ ,  $R_2$ ,  $R_3$ , and  $R_4$  are adjusted for some other maximum sensitivity angle the nominal reach is different than that indicated by the taps. The reach  $Z_\theta$ , varies with the maximum sensitivity angle,  $\theta$ , as follows:

$$Z_\theta = \frac{TS \sin \theta (1 + M)}{\sin 75^\circ}$$

#### 3.3. Tap Plate Markings

##### 3.3.1. $T_A$ , $T_B$ , $T_C$ (Positive Sequence)

For 1.0 - 31 Ohms range — 1.2, 1.5, 2.1, 3.0, 4.5, 6.3, 8.7

For 2. - 4.25 Ohms Range — .23, .307, .383, .537, .69, .92, 1.23

##### 3.3.2. $T_0$ (Zero Sequence)

For 1.0 - 31 Ohms Range — 3.60, 4.5, 6.3, 9.0, 13.5, 18.9, 26.1

For .2 - 4.35 Ohms Range — 0.69, 0.92, 1.15, 1.61, 2.07, 2.76, 3.69

$$\frac{(S_A \text{ and } S_C)}{1 \quad 2 \quad 3}$$

$$\pm \text{ Values between taps } \frac{(M_A, M_B, M_C, M_O)}{.03 \quad .09 \quad .06}$$

### 3.4. Time Curves and Burden Data

#### 3.4.1. Operating Time

The speed of operation is shown in Figure 10. The curves indicate the time in milliseconds required for the relay to provide an output for tripping after the occurrence of a fault at any point on a line within the relay setting.

Current Circuit Rating in Amperes  
(All Ranges, All Settings)

Continuous — 10 Amperes  
1 Second — 240 Amperes

#### 3.4.2. Burden

The potential burden at 69 volts varies from a maximum of 1.4 volt-amperes at S = 1 setting to a minimum of 0.42 volt-amperes based on 69 volts line-to-neutral per phase. Current burden varies from a maximum of 4.5 volt-amperes at 5 amperes for a maximum T-setting to a minimum of 0.60 volt-amperes for a minimum T-setting. This burden applies to each phase and residual current circuit. Dc current burden is .07 amperes at all rated voltages in non-trip condition.

#### 3.4.3. Trip Circuit Constants

1 Ampere I.C.S. — 0.1 Ohms dc Resistance

## 4. CALCULATIONS AND SELECTION OF SETTING

Relay reach is set on the tap plate. Maximum sensitivity angle,  $\theta$ , is set for 75° (current lagging voltage) in the factory. This adjustment need not be disturbed for line angles of 65° or higher. For line angles below 65°. Set  $\theta$  for a 60° maximum sensitivity angle, by adjusting R<sub>1</sub>, R<sub>2</sub>, R<sub>3</sub> and R<sub>4</sub> as per calibration procedure for Zone1 application only. Set Zone1 reach to be 85% of the line, if S = 1 is used; 75% if S = 2 or 3 are used. Do not change angle for pilot trip or Zone2, or Zone3 applications.

Assume a desired balance point which is 85% of the total length of the line. The general formulas for setting the ohms reach of the relay are:

$$Z_1 = Z_{1L} \frac{0.85R_C}{R_V} ; Z_0 = Z_{0L} \frac{0.85R_C}{R_V}$$

The terms used in this formula and hereafter are defined as follows:

Z<sub>0</sub> = Zero sequence ohmic reach to be used for relay settings.

Z<sub>1</sub> = Positive sequence ohmic reach to be used for relay settings.

Z<sub>1, 0</sub> = TS (1 + M) = the tap plate setting.

T = Compensator tap value.

S = Auto-transformer tap value.

$\theta$  = Maximum sensitivity angle setting of the relay.

$\pm M$  = Compensator tertiary tap value. (This is a per unit value and is determined by the sum of the values between the "L" and the "R" leads. The sign is positive when "L" is above "R" and acts to raise the Z setting. The sign is negative when "R" is above "L" and acts to lower the "Z" setting).

Z<sub>1L</sub> = Positive sequence ohms per phase of the total line section, referred to the primary.

Z<sub>0L</sub> = Zero sequence ohms per phase of the total line section, referred to the primary.

R<sub>C</sub> = Current transformer ratio.

R<sub>V</sub> = Voltage transformer ratio.

The following procedure should be followed in order to obtain an optimum setting of the relay.

Zone 1 Setting (SDG-1T and SDG-2T Relays)

1a. Establish the desired values of Z<sub>1</sub> and Z<sub>0</sub> as above (available from transmission line data) and desired maximum sensitivity angle  $\theta^\circ$ .

1b. Determine the desired tap plate value Z' using the formula a:

$$Z_1 = Z_{1\theta} \frac{\sin 75^\circ}{\sin \theta} \text{ and } Z_0 = Z_{0\theta} \frac{\sin 75^\circ}{\sin \theta}$$

$\theta$  = Angle to which relay is recalibrated

Then, for factory calibration

$$\theta = 75^\circ, Z_1 = Z_{1\theta} \text{ and } Z_0 = Z_{0\theta}$$

2. Now refer to Table II or IV giving preferred Zone1 settings for the SDGT relays. If the desired reach exceeds the relay range for S = 1, use S = 2 and Table III or V (set for 75% of line).
- 2a. Locate a table value for relay reach nearest to the desired  $Z_1$  value (it will always be within 1.5% of the desired value.)
- 2b. From this table read off the "S", "T" and "M" settings. The "M" column includes additional information for the "L" and "R" lead setting for the specified "M" value. If the desired settings cannot be found on this table proceed to Table III or V to find the desired setting in this case. The relay reach must now be reduced from 85 to 75 percent to avoid overreach on two phase-to-ground faults on high fault resistance faults.
- 2c. Recheck relay settings for  $Z_1$  and  $Z_0$  using equation:

$$Z = TS(1 + M)$$

For example, assume the desired reach,

$Z_{1\theta}$  is 7 ohms at  $60^\circ$  (step 1a) and  $Z_{0\theta}$  is 21 ohms at  $60^\circ$ .

Next step is (1b). Making correction of maximum sensitivity angle of the relay to match the characteristic angle of the line ( $60^\circ$ ) that is different from factory setting of  $75^\circ$ , we find the relay tap setting.

$$Z_1 = 7 \times 1.11 = 7.77 \text{ ohms}$$

$$Z_0 = 21 \times 1.11 = 23.31 \text{ ohms}$$

This procedure is followed when  $R_1, R_2, R_3, R_4$  settings are changed, otherwise follow alternative procedure below.

Step (2a). In Table IV we find 7.65 to be the nearest value to 7.77 ohms.

$$100 \times \frac{7.65}{7.77} = 98.8\% \text{ or } 1.2\% \text{ from the desired value.}$$

For the  $Z_0$  selection find the nearest value to 23.31 ohms using the same S setting as above. 23.0 ohms is the nearest value.

$$100 \times \frac{23.0}{23.31} = 98.8\% \text{ or } 1.2\% \text{ within the desired value.}$$

Step (2b). From Table IV read off:

$$\begin{aligned} S &= 1 \\ T &= 8.7 & T_0 &= 26.1 \\ M &= -.12 & M_0 &= -.12 \end{aligned}$$

The "R" lead should be connected over "L" lead, with "L" lead connected to "0" tap and "R" lead to tap "09". (The sum of the values between L and R is 0.12).

Step (2c). Recheck Settings.

$$Z_1 = TS(1 \pm M) = 1 \times 8.7 (.88) = 7.65 \text{ and}$$

$$Z_0 = 1 \times 26.1 (.88) = 23.0$$

$$Z_1 = Z_{1\theta} \frac{\sin 60^\circ}{\sin 75^\circ} \quad 7.65 \times 900 = 6.90 \text{ ohms at } 60^\circ$$

$$Z_0 = Z_{0\theta} \frac{\sin 60^\circ}{\sin 75^\circ} = 23.0 \times 900 = 20.7 \text{ ohms at } 60^\circ$$

Where balance point product of  $3I_0 Z_1 < 40$  volts (where  $Z_1$  is positive sequence relay setting and  $3I_0$  is zero sequence current in the relay for L-G fault) disconnect the phase-to-phase desensitizer and set Zone1 as calculated.

#### 4.1. Alternative Calculations and Settings

If it is desired to avoid recalibration of the relay maximum sensitivity setting, the following procedure should be followed.

Follow Step (1a) as above.

Change Step (1b) to compute desired reach according with equation:

$$Z = \frac{Z}{\cos(75 - \theta)}$$



**Table 11**  
**.2 - 4.35 OHMS RELAY RANGE**

POSITIVE SEQUENCE (Z <sub>1</sub> ) S = 1								ZERO SEQUENCE (Z <sub>0</sub> ) S = 1								M		CONNECT		
																		“L” LEAD TO TAP	“R” LEAD TO TAP	
T	.230	.307	.383	.537	.69	.92	1.23	T <sub>0</sub>	.69	.921	1.15	1.61	2.07	2.76	3.69	+M	−M			
	.272	.362	.452	.632	.815	1.09	1.45		.815	1.09	1.36	1.90	2.44	3.26	4.40	+18		.06	0	
	.264	.352	.441	.617	.794	1.06	1.41		.794	1.06	1.32	1.85	2.38	3.18	4.25	+15		.06	.03	“L” OVER “R”
	.258	.344	.430	.601	.772	1.03	1.38		.772	1.03	1.29	1.80	2.32	3.10	4.15	+12		.09	0	
	.251	.335	.418	.585	.754	1.00	1.34		.754	1.00	1.25	1.76	2.26	3.00	4.04	+09		.09	.03	
	.244	.325	.405	.570	.732	.975	1.30		.732	.975	1.22	1.71	2.20	2.92	3.92	+06		.06	.09	
	.237	.316	.396	.555	.710	.950	1.27		.710	.950	1.18	1.66	2.13	2.84	3.80	+03		.03	0	
	.230	.307	.383	.537	.69	.920	1.23		.69	.921	1.15	1.61	2.07	2.76	3.69	0	0	0	0	
	.223	.298	.370	.520	.670	.892	1.19		.670	.892	1.12	1.56	2.00	2.68	3.58		−.03	0	.03	“R” OVER “L”
	.216	.288	.360	.505	.650	.865	1.15		.650	.865	1.08	1.52	1.95	2.60	3.46		−.06	.09	.06	
	.209	.280	.348	.488	.627	.840	1.12		.627	.840	1.05	1.47	1.88	2.51	3.36		−.09	.03	.09	
	.202	.270	.336	.472	.607	.810	1.08		.607	.810	1.01	1.42	1.82	2.43	3.25		−.12	0	.09	
	1.95	.260	.324	.456	.587	.782	1.05		.587	.782	.980	1.37	1.76	2.35	3.14		−.15	.03	.06	
	.188	.252	.314	.440	.565	.755	1.01		.565	.755	.940	1.32	1.70	2.26	3.02		−.18	0	.06	

**Table 1II**  
**.2 - 4.35 OHM RELAY RANGE**

POSITIVE SEQUENCE SETTINGS (Z <sub>1</sub> )								ZERO SEQUENCE SETTINGS (Z <sub>0</sub> )												M		CONNECT		
S = 2								S = 3		S = 2								S = 3				“L” LEAD TO TAP	“R” LEAD TO TAP	
T	.230	.307	.383	.537	.69	.92	1.23	.92	1.23	T <sub>0</sub>	.69	.921	1.15	1.61	2.07	2.76	3.69	2.76	3.69	+M	−M			
	.544	.724	.905	1.26	1.63	2.17	2.90	3.26	4.40		1.63	2.17	2.72	3.80	4.90	6.50	8.70	9.80	12.1	+18		.06	0	“L” OVER “R”
	.528	.704	.880	1.23	1.59	2.12	2.82	3.18	4.25		1.59	2.12	2.65	3.70	4.76	6.35	8.48	9.55	12.7	+15		.06	.03	
	.516	.688	.860	1.20	1.55	2.06	2.76	3.10	4.15		1.55	2.06	2.58	3.60	4.65	6.20	8.25	9.30	12.4	+12		.09	0	
	.502	.670	.835	1.17	1.51	2.00	2.68	3.00	4.04		1.51	2.00	2.50	3.50	4.52	6.00	8.05	9.05	12.1	+09		.09	.03	
	.488	.650	.810	1.13	1.46	1.95	2.60	2.92	3.92		1.46	1.95	2.44	3.41	4.40	5.85	7.80	8.80	11.8	+06		.06	.09	
	.474	.632	.790	1.10	1.42	1.90	2.53		3.80		1.42	1.90	2.37	3.32	4.26	5.70	7.60		11.4	+03		.03	0	“R” OVER “L”
	.460	.614	.766	1.07	1.38	1.84	2.46		3.69		1.38	1.84	2.30	3.22	4.14	5.52	7.38		11.1	0	0	0	0	
	.446	.596	.740	1.04	1.34	1.78	2.40		3.58		1.34	1.78	2.24	3.12	4.02	5.35	7.15		10.7		-03	0	.03	
	.432	.576	.716	1.01	1.30	1.73	2.32		3.46		1.30	1.73	2.16	3.02	3.90	5.16	6.94		10.4		-06	.09	.06	
	.418	.560	.695	.975	1.25	1.67	2.24		3.36		1.25	1.67	2.09	2.94	3.78	5.00	6.70		10.1		-09	.03	.09	
	.404	.540	.674	.940	1.21	1.62	2.17				1.21	1.62	2.02	2.83	3.66	4.85	6.50		9.8		-12	0	.09	
	.390	.520	.650	.910	1.17	1.56	2.10				1.17	1.56	1.95	2.74	3.55	4.67	6.27		9.4		-15	.03	.06	
	.376	.504	.625	.880	1.13	1.50	2.08				1.13	1.50	1.79	2.64	3.40	4.50	6.05		9.1		-18	0	.06	



**Table 1V**  
**1.1 - 31 OHMS RELAY RANGE**

	POSITIVE SEQUENCE (Z <sub>1</sub> )							ZERO SEQUENCE (Z <sub>0</sub> )								M		CONNECT		
T	S = 1							S = 1										“L” LEAD TO TAP	“R” LEAD TO TAP	
	1.2	1.5	2.1	3.0	4.5	6.3	8.7	T <sub>0</sub>	3.6	4.5	6.3	9.0	13.5	18.9	26.1					
	1.42	1.77	2.48	3.54	5.3	7.43	10.2		4.25	5.30	7.45	10.6	15.9	22.2	30.8	+18		.06	.0	“L” OVER “R”
	1.38	1.73	2.42	3.45	5.17	7.25	10.0		4.15	5.17	7.25	10.4	15.5	21.7	30.0	+15		.06	.03	
	1.34	1.68	2.36	3.36	5.04	7.05	9.75		4.05	5.04	7.05	10.1	15.1	21.2	29.3	+12		.09	0	
	1.31	1.64	2.29	3.27	4.90	6.89	9.50		3.94	4.90	6.89	9.81	14.7	20.6	28.4	+09		.09	.03	
	1.27	1.59	2.22	3.18	4.77	6.70	9.25		3.82	4.77	6.70	9.54	14.3	20.0	27.7	+06		.06	.09	
	1.24	1.55	2.16	3.09	4.64	6.50	8.95		3.71	4.64	6.50	9.27	13.9	19.5	26.9	+03		.03	0	“R” OVER “L”
	1.20	1.5	2.10	3.00	4.50	6.30	8.70		3.6	4.0	6.30	9.0	13.5	18.9	26.1	0	0	0	0	
	1.16	1.45	2.04	2.91	4.36	6.10	8.45		3.50	4.36	6.10	8.73	13.1	18.3	25.2		-.03	0	.03	
	1.13		1.97	2.82	4.23	5.90	8.15		3.38		5.90	8.46	12.7	17.7	24.5		-.06	.09	.06	
	1.09		1.91	2.73	4.10	5.74	7.90		3.27		5.74	8.19	12.3	17.2	23.7		-.09	.03	.09	
	1.06		1.85	2.64	3.96	5.55	7.65		3.16		5.55	7.92	11.9	16.6	23.0		-.12	0	.09	
	1.02		1.77	2.55	3.82	5.35			3.06		5.35	7.65	11.5	16.0			-.15	.03	.06	
	.99				3.69				2.95				11.1				-.18	0	.06	



**Table 1**  
**1.1 - 31 OHM RELAY RANGE**

POSITIVE SEQUENCE SETTINGS (Z <sub>1</sub> )								ZERO SEQUENCE SETTINGS (Z <sub>0</sub> )												M		CONNECT		
S = 2								S = 3		S = 2								S = 3				“L” LEAD TO TAP	“R” LEAD TO TAP	
T	1.2	1.5	2.1	3.0	4.5	6.3	8.7	6.3	8.7	T <sub>0</sub>	3.6	4.5	6.3	9.0	13.5	18.9	26.1	18.9	26.1	+M	-M			
	2.84	3.54	4.96	7.08	10.62	14.9	20.5	22.3	30.8		8.50	10.6	14.9	21.2	31.8	44.5	61.5	66.6	92.5	+18		.06	0	“L” OVER “R”
	2.76	3.46	4.84	6.90	10.35	14.5	20.0	21.6	30.0		8.30	10.34	14.5	20.7	31.0	43.5	60.0	65.1	90.0	+15		.06	.03	
	2.68	3.36	4.72	6.72	10.08	14.1	19.5	21.2	29.3		8.10	10.08	14.1	20.2	30.2	42.4	58.5	63.6	87.5	+12		.09	0	
	2.62	3.28	4.58	6.54	9.81	13.8	19.0		28.4		7.88	9.80	13.8	19.6	29.4	41.2	56.8		85.2	+09		.09	.03	
	2.54	3.18	4.44	6.36	9.54	13.4	18.5		27.7		7.64	9.54	13.4	19.1	28.6	40.0	55.3		83.0	+06		.06	.09	
	2.48	3.10	4.32	6.18	9.27	13.0	17.9		27.0		7.42	9.28	13.0	18.5	27.8	39.0	53.8		80.5	+03		.03	0	“R” OVER “L”
	2.4	3.0	4.20	6.0	9.0	12.6	17.4		26.1		7.20	9.0	12.6	18.0	27.0	37.8	52.2		78.3	0	0	0	0	
	2.32	2.90	4.08	5.82	8.73	12.2	16.9		25.2		7.00	8.72	12.2	17.5	26.2	36.6	50.5		75.8		-.03	0	.03	
	2.26		3.95	5.64	8.46	11.8	16.3		24.5		6.76		11.8	16.9	25.4	35.4	49.0		73.5		-.06	.09	.06	
	2.18		3.82	5.46	8.19	11.5	15.8		23.7		6.54		11.5	16.4	24.6	34.4	47.5		71.0		-.09	.03	.09	
	2.12		3.70	5.28	7.92	11.1	15.3		23.0		6.32		11.1	15.8	23.8	32.2	45.8		68.8		-.12	0	.09	
	2.04		3.54	5.10	7.65	10.7			22.7		6.12		10.7	15.3	23.0	32.0					-.15	.03	.06	
	1.98				7.38										22.2						-.18	0	.06	

**NOTE: Do not use equation to predict relay response for angles more than 15° away from  $\theta$ .**

$$\text{Then } Z_1 = \frac{7}{\cos(75^\circ - 60^\circ)} = \frac{7}{.965} = 7.25$$

$$Z_0 = \frac{21}{\cos(75^\circ - 60^\circ)} = \frac{21}{.965} = 21.75$$

Step 2a as above from Table IV you will find 7.25 value and 21.75 ohm-values as the exact values.

Step (2b) from Table IV read off:

$$S = 1$$

$$T = 6.3 \quad T_0 = 18.9$$

$$M = +.15 \quad M_0 = +.15$$

Step (2c) Recheck Settings.

$$Z_1 = Z_1 \cos(75^\circ - \theta) = 7.25 \times .965 = 7 \text{ ohms}$$

$$Z_0 = Z_0 \cos(75^\circ - \theta) = 21.75 \times .965 = 21 \text{ ohms}$$

#### 4.1.1. Zone 2 and 3 Settings or Pilot Trip Applications

For Zone 2 and 3 or pilot trip settings use a procedure similar to alternative for Zone 1 described above. Tables II to V give the required settings. ***There is no need to recalibrate relay for difference in maximum torque angle when alternative procedure is used.***

**NOTE: The S setting must be the same for both the positive and zero sequence reach.**

## 4.2. Setting The Relay

The SDGT relays require settings for the four compensators ( $T_A$ ,  $T_B$ ,  $T_C$  and  $T_O$ ), the three auto-transformer primaries ( $S_A$ ,  $S_B$  and  $S_C$ ), and the four compensator tertiaries ( $M_A$ ,  $M_B$ ,  $M_C$ , and  $M_O$ ). All of these settings are made with taps on the tap plate, with relay deenergized.

### 4.2.1. Compensator ( $T_A$ , $T_B$ , $T_C$ , $T_O$ and $M_A$ , $M_B$ , $M_C$ , $M_O$ )

Each set of compensator primary  $T_A$ ,  $T_B$ ,  $T_C$ ,  $T_O$ , taps terminates in inserts which are grouped on a socket and form approximately three-quarters of a circle around a center insert which is the common connection for all of the taps. Electrical connections between common insert and tap inserts are made with a link that is held in place with two connector screws, one

in the common and one in the tap. A compensator tap setting is made by loosening the connector screw in the center. Before removing the screw open switches 12 through 19 to bypass the current around the relay. Remove the connector screw in the tap end of the link, swing the link around until it is in position over the insert for the desired tap setting, replace the connector screw to bind the link to this insert, and retighten the connector screw in the center. Since the link and connector screws carry operating current, be sure that the screws are turned to bind snugly. Compensator secondary tap connections are made through two leads identified as L and R for each compensator. These leads come out of the tap plate each through a small hole, one on each side of the vertical row of "M" tap inserts. The lead connectors are held in place on the proper tap by connector screws.

Values for which an "M" setting can be made are from -.18 to +.18 in steps of .03. The value of a setting is the sum of the numbers that are crossed when going from the R lead position to the L lead position. The sign of the "M" value is determined by which lead is in the higher position on the tap plate. The sign is positive (+) if the L lead is higher and negative (-) if the R lead is higher.

An "M" setting may be made in the following manner. Remove the connector screws so that the L and R leads are free. Refer to Table II through Table V to determine the desired "M" value. Neither lead connector should make electrical contact with more than one tap at a time.

### 4.2.2. Line Angle Adjustment

Maximum sensitivity angle is set for 75° (current lagging voltage) in the factory. This adjustment need not be disturbed for line angles of 65° or higher. For line angles below 65° set for 60° maximum sensitivity angle by adjusting the compensator loading resistors  $R_1$ ,  $R_2$ ,  $R_3$ ,  $R_4$ . Refer to repair calibration under "Maximum Torque Angle Adjustment", when a change in maximum sensitivity angle is desired. For Zone 2 and 3 or pilot trip application no need to recalibrate relay.

In general, the change in maximum torque angle adjustment, if desired, can be avoided. In this case the tap plate setting of the relay is adjusted to compensate for difference in the maximum torque angle of the relay (75°) and the characteristic angle of the line  $\theta$  according to the following equation: (In this case, follow procedure outlined under alternative calculations and settings).

$$Z_{1,0} = \frac{Z_{1,0}}{\cos(75^\circ - \theta)}$$

Here  $Z_{1,0}$  – Tap Plate Setting

$Z_{1,0}$  – Desired Ohmic Reach

#### 4.2.3. Phase-to-Phase Desensitizer

When it is necessary to disconnect this circuit unsolder or cut terminal 8 to the 2Ø-G board (see Figure 24) for SDG-2T or open 2Ø-G switch for SDGT-1T.

### 5. INSTALLATION

The relays should be mounted on switchboard panels or their equivalent in a location free from dirt, moisture, excessive vibration and heat. Mount the relay by means of the mounting stud for the type FT projection case or by means of the four mounting holes on the flange for the semi-flush type FT case. Either the stud or the mounting screws may be made directly to the terminals by means of screws for steel panel mounting or to the terminal stud furnished with the relay for thick panel mounting. The terminal stud may be easily removed or inserted by locking two nuts on the stud and then turning the proper nut with a wrench. For outline and drilling panel see Figure 12.

For detailed information on the FT case refer to IL 41-076.

#### 5.1. External Connections

Figure 11 shows typical connection for single zone protection using and SDG relay. SPP capacitors are not required unless surge voltage may exceed 2500 volts.

#### 5.2. Acceptance Test

Acceptance tests consist of:

1. A visual inspection
2. "Push-button" check (for SDG-2T only).
3. An electrical test to make certain that the relay measures the balance point impedance accurately.

##### Step 1. Visual Inspection

Give a visual check to the relay to make sure that there are no loose connections, broken resistors or broken wires.

.2-4.25 Ohm Relay	1.0-31.0 Ohm Relay
All T = 1.23	All T = 8.7
All T <sub>0</sub> = 3.69	T <sub>0</sub> = 26.1
All S = 1	All S = 1
All M = +.18	All M = +.18

##### Step 2. Push-button Check

**For SDG-2T only** open relay terminal 10 and 11.

Using the test connections of Figure 9. Connect the ac voltages as per test No. 1. No current connections are required. Connect the rated dc voltages as shown. Open circuit connections to terminal No. 7. Set  $V_{BN} = V_{CN} = 70$  volts. Depress the white push-button. The push-button should light. If the push-button does not light, observe contact operation. If there is an operation but the lamp does not light this indicates a fault in the push-button circuit. If there is no fault indication proceed with the electrical test to isolate the fault in the push-button circuit or the relay.

##### Step 3. Electrical Tests

##### Distance Unit

Tripping is indicated by contact operation. Refer to Figure 9 for all test connections.

##### For .2-4.35 Ohm Relay

- A. Use connections for Test No. 5 and set  $V_{AN}$  voltage = 20 volts.  $V_{BN} = V_{CN} = 70$  volts. Set the phase shifter for 75° current lagging voltage.

The relay current required to make the trip should be between 8.0 - 8.6 amp.

- B. Use connections for Test No. 6 and set  $V_{BN}$  voltage = 20 volts.  $V_{AN} = V_{CN} = 70$  volts. Set the phase shifter as above. The relay trip current should be 8.0-8.6 amps.
- C. Use connections for Test No. 7 and set  $V_{CN} = 20$  volts  $V_{AN} = V_{BN} = 70$  volts. Set the phase shifter as above. The SDG relay trip current should be 8.0-8.6 amps.

##### For 1.0 - 31.0 Ohm Relay

- A. Use connections for Test No. 5 and set  $V_{AN} = 60$  volts and  $V_{BN} = V_{CN} = 70$  volts in proper phase sequence. Set the phase shifter for 75° current lagging voltage. The relay trip current should be 3.35 - 3.65 amperes.



- B. Use connections for Test No. 6 and set  $V_{BN} = 60$  volts and  $V_{AN} = V_{CN} = 70$  volts. Set the phase shifter as above. The relay trip current should be 3.35 - 3.65 amperes.
- C. Use connections for Test No. 7 and set  $V_{CN} = 60$  volts and  $V_{AN} = V_{BN} = 70$  volts. Set the phase shifter as above. The relay trip current should be 3.35 - 3.65 amperes.

If the electrical response is outside the limits a more complete series of tests outlined in the section titled "Calibration" may be performed to determine which component is faulty or out of calibration.

If you desire to check relay response at some other settings use following equation for the trip value of current.

$$I = \frac{3V_{LN}}{(2+p)Z_1}, \text{ where } p = \frac{Z_0}{Z_1}$$

$Z_0$  = Zero sequence reach

$Z_1$  = Positive sequence reach (in above cases  $p = 3$ )

$V_{LN}$  = desired fault voltage



**If testing requires trip current over 15 amps. over prolonged periods, it is recommended that a heavy short lead be connected from terminal 19 to the center tap of  $T_0$  socket. Also connect a jumper lead from terminal 17 to terminal 1 on the large printed circuit board for SDG-1T relay. (Lower set of terminals rear view).**

### 5.3. Maximum Torque Angle

Maximum torque angle check is optional. In general, this check is complicated for SDG-1T and SDG-2T relays by the presence of transient blocking circuit, and the two-phase-to-ground fault desensitizer circuit.

The presence of transient blocking circuit requires that check for maximum torque angle should be made going from non-tripping to tripping condition at each end of the tripping range of the relay under test.

Since the lab method of testing as used here presents artificial voltage conditions, under certain voltage and phase angle conditions two-phase-to-ground desensitizer will distort phase angle response; hence, it is required to disable the 2 $\phi$ -G circuit for SDG-1T by opening the front switch OR connect a 10K resistor from the cathode of Z6 on the 2 $\phi$  to Gnd to module to relay terminal 2 for SDG-2T relays.

To disable transient blocking circuit short out resistor R48 on large printed circuit board for SDG-1T and SDG-2T.

#### 5.3.1. Phase A Check

Use connection No. 5. Relay tap settings should be the same as before. For all ranges set  $V_{AN} = 20$  volts,  $V_{BN} - V_{CN} = 70$  volts.

Set current for 1-30 ohm relay or 1.54 amp, and for .2-4.35 ohm relay for 11 amp. Set phase-shifter for 75° current lagging  $V_{AN}$  voltage. Turn phase-shifter toward 0°. After relays have dropped out, reverse phase-shifter rotation and note the angle ( $\phi_1$ ) at which relay is fully tripped. Rotate the phase-shifter past the 75° until relay resets again. Then rotate phase-shifter back toward 75° until relay is fully tripped. Note the angle again ( $\phi_2$ ).

Maximum torque angle is equal then to

$$\frac{\phi_1 + \phi_2}{2} = 75^\circ (\pm 5^\circ)$$

Any other T setting may be used, except use 130% current of the trip current at 75° angle.

#### 5.3.2. Phase B Check

Use connection No. 6 Set  $V_{BN} = 20$  volts.  $V_{AN} = V_{CN} = 70$  volts. Otherwise follow the same procedure as for Phase A.

#### 5.3.3. Phase C Check

Use connection No. 7. Set  $V_{CN} = 20$  volts,  $V_{AN} = V_{BN} = 70$  volts. Otherwise follow the same procedure as for Phase A. When completed remove jumper from R48 resistor.

### 5.4. Two-phase-to-ground Desensitizer Check

Use connection No. 5 except no current connection is required for this test.

### 5.5. AB – Combination

Set  $V_{CN} = 70$  volts.  $V_{AN} = V_{BN} = 10$  volts. Check dc voltage on small PC board located just behind R1-R4 potentiometers terminal “10” (positive) located behind R1 potentiometer (second from the bottom) and relay terminal “2”. It should measure 10 to 22 volts. Reset  $V_{AN} = V_{BN} = 70$  volts. Dc output should disappear.

#### 5.5.1. BC – Combination

Same check as for AB except first set  $V_{AN} = 70$  volts.  $V_{BN} = V_{CN} = 10$  volts and then reset  $V_{BN} = V_{CN} = 70$  volts.

#### 5.5.2. CA – Combination

Same check as for AB except first set  $V_{AN} = 70$  volts.  $V_{CN} = V_{AN} = 10$  volts and then reset  $V_{CN} = V_{AN} = 70$  volts.

### 5.6. Overcurrent Unit

Check operation of the overcurrent unit by using test connection No. 5 of Figure 9. Set  $V_{AN} = 0$ ,  $V_{BN} = V_{CN} = 70$  volts. The .2 - 4.35 ohm relay should operate at .75 - .83 amperes, and the 1 - 31.0 ohms relay should operate at .37 - .420 amperes. If not, check adjustment of R63 potentiometer.

### 5.7. Indicating Contactor Switch (ICS)

With the SDGT relay tripping, pass sufficient dc current through the trip circuit to close the contact of the ICS. This value of current should be not less than 1.0 ampere or greater than 1.2 amperes, for the 1 ampere ICS. The current should not be greater than the particular ICS tap setting being used for the 0.2 — 2.0 ampere ICS. The operation indicator target should drop freely.

The contact gap should be approximately 0.047” for the 0.2 - 2.0 ampere unit and 0.07” for the 1.0 ampere unit between the bridging moving contact and the adjustable stationary contacts. The bridging moving contact should touch both stationary contacts simultaneously.

## 6. ROUTINE MAINTENANCE

The relays should be inspected periodically, at such intervals as may be dictated by experience, to insure that the relays have retained their calibration and are in proper operating condition.

### In-Service Test

#### (If Relay is Set for S = 1 Only) (SDG-2T Only)

In-service testing is performed as follows:

1. Open relay trip circuit by opening red handle switch No. 11.
2. Open relay voltage terminal 7.
3. Press white push-button. Push-button light should light.

This test checks the operation of the magnitude comparator and output circuitry.

When push-button is used for direct breaker trip, depress push-button for short time only.

## 7. REPAIR CALIBRATION

Use the following procedure for calibrating the relay if the relay has been taken apart for repairs or the adjustments disturbed. *Printed circuit boards styles and components are identified on Figures 5 to 8. Component location as per Figures 20 to 27.*

For easier access to the parts, the relay should be tested out of the case.

Use Figure 15 for Test Point Traces reference.

### Part A Preliminary Settings

1. Remove the printed circuit board(s) (PCB) in the rear of the relay.
2. Set  $R_1$ ,  $R_2$ ,  $R_3$ ,  $R_4$  potentiometers fully counter-clockwise for maximum resistance.
3. Set relay for  $S = 1$ ,  $M = +18$  (“L” lead over “R” lead), all  $T = 8.7$ ,  $T_0 = 26.1$  for the 1.0 - 31.0 ohm relays and for the .2 - 4.35 ohms relay all  $T = 1.23$   $T_0 = 3.69$ .

### Part B Voltage Circuit Tests

1. Apply 3-phase balanced voltages as per test 1 of Figure 9 except no current is applied.
2. Set  $V_{AN} = V_{BN} = V_{CN} = 70$  volts ac. Measure following ac voltages.

From relay terminal 6 to  $S_A = 1$  Tap 70 ( $\pm 1$ ) Volts.

From relay terminal 6 to  $S_A = 2$  Tap 140 ( $\pm 2$ ) volts.

From relay terminal 6 to  $S_A = 3$  Tap 210 ( $\pm 3$ ) volts.

From relay terminal 6 to  $R_A$  lead 39.2 ( $\pm 5$ ) volts.

Repeat the same measurements for  $S_B$ ,  $S_C$ , and  $R_B$ ,  $R_C$  leads.

3. Disconnect  $R_0$  lead from  $M_0 = 0$  Tap and measure the voltage from relay terminal "4" to the  $R_0$  lead. It should be below 0.7 volts ac.
4. Apply rated dc voltage to the relay. Check the dc voltage across the lower set of plug-in terminals (rear view) "5" and "1" for the SDG-1T, -2T, and -4T relays. It should measure 20 ( $\pm 2$ ) volts.

**Note:** 250 V dc relay requires external resistor.

5. Plug in the lower and upper boards.

### Part C Potentiometer Adjustments



**All potentiometers are locked type and should be unlocked before adjustment and locked after adjustment is complete.**

1. Set R5, R6, R7, R8 for maximum setting (counterclockwise).
2. If no scope is available, measure the voltages with a Rectox-type voltmeter across the specified terminals of the small upper terminal board located in the rear. All the following measurements are done on the small upper board. Terminal numbers refer to this board only. Use of scope is preferred.

#### ■ R5 Adjustment

Measure the voltage across terminals 2 and 3. Adjust R5 until voltages across 4 and 2 and 4 and 3 are equal ( $\pm 0.1$  volt) to each other and are within 1.0 volt of voltage across 2 and 3. If oscilloscope is available, observe voltage across R9 and set R5 so that peaks on the 360 Hz ripple are in ascending order.

#### ■ R6 Adjustment

Measure the voltage across terminals 6 and 8. Adjust R6 until voltages across terminals 7 and 6 and 7 and

8 are equal ( $\pm 1$  volt) to each other and are within 1.0 volt of voltage across 6 and 8. If an oscilloscope is available observe voltage across R10 and set R6 so that peaks are in ascending order.

#### ■ R7 Adjustment

Measure the voltage across terminals 17 and 18. Adjust R7 until voltages across terminals 15 and 18 and 15 and 17 are equal ( $\pm 0.1$  volt) to each other and are within 1.0 volt of voltages across 17 and 18. If oscilloscope is available observe voltage across R11 and set R7 so that peaks are in ascending order.

#### ■ R8 Adjustment

Reduce  $V_{AN}$  to zero and measure the voltage across terminals 11 and 12. Adjust R8 until voltages across terminals 14 and 11 and 14 and 12 are equal ( $\pm 0.1$  volt) to each other and are within 1.0 volt of voltage across 11 and 12. If oscilloscope is available observe voltage across R12 and set R8 so that the two valleys in the middle are equal.

### Maximum Torque Angle Adjustment

Disconnect all R and L leads and jumper relay terminals 5 and 6.

#### ■ R1 Adjustment

For the 1.0 - 31.0 ohm relay use the No. 1 test connection of Figure 9. Apply 5.08 amp ac current to the relay. Set  $V_{AN}$  45 volts and  $V_{BN} = V_{CN} = 0$  volts. Set the phase-shifter for  $75^\circ$  current lagging voltage.

For .20 - 4.35 ohm relay use the same procedure as above except set the current for 15.65 amp. and  $V_{AN} = 20$  volts.

Insert an ac voltmeter of 0.3 volts range between  $R_A$  and  $L_A$  leads. Adjust R1 potentiometer for a minimum ("null" reading) and lock R1 in place. Vary current slightly to achieve lower "null" reading.

For other angles multiple current by:

$$K = \frac{\sin 75}{\sin \theta}$$

where  $\theta$  = desired maximum torque angle, for  $\theta = 60^\circ$   $K = 1.11$ .

### ■ R-2 Adjustment

Use No. 2 test connections of Figure 9. Set  $V_{BN} = 45$  volts and  $V_{AN} = V_{BN} = 0$  volts. Set  $I_B = 5.08$  amps. 75° lagging  $V_{BN}$ . (Modify voltage and current settings for the .2 - 4.35 ohm relay as above). Measure the voltage between  $R_B$  and  $L_B$  leads. Adjust R2 potentiometer for a minimum ("null" reading) and lock R2 in place.

### ■ R3 Adjustment

Use No. 3 test connections of Figure 9. Set  $V_{CN} = 45$  volts and  $V_{AN} = V_{BN} = 0$  volts.  $I_C = 5.08$  amp. 75° lagging  $V_{CN}$ . (Modify voltage and current for the .2 - 4.35 ohm relay as above).

Measure the voltage between  $R_C$  and  $L_C$  leads. Adjust R3 potentiometer for a minimum ("null" reading) and lock R3 in place.

### ■ R4 Adjustment

Remove jumper from relay terminals 5 and 6. Use the No. 4 test connections of Figure 7. Connect all "L" and "R" leads back to previous setting, except  $R_O$  lead. Set  $V_{CN} = 0$  and  $V_{AN} = V_{BN} = 70$  volts. Set  $I_C = 2.34$  amp. 75° lagging  $V_{CN}$ . (For the .2 to 4.35 relay set  $V_{CN} = 0$  and  $V_{BN} = V_{AN} = 45$  volt.  $I_C = 9.9$  amperes). Measure the voltage between  $R_O$  and the lowest M0 tap marked "0".

Adjust the R4 potentiometer for minimum voltage ("null" reading) and lock R4 in place.

### Part D M Taps Check

Use a Rectox-Type Voltmeter.

Open all "R" and "L" leads.

#### For 1 - 30 ohm Relay

$M_A$  Taps — Use test connection No. 1 of Figure 9. Pass 10 amp. current through the relay. The voltages should read as follows:

1.5 ( $\pm 0.2$ ) volts between 0 tap and .03 tap.

6.0 ( $\pm 0.6$ ) volts between 0 tap and .09 tap

9.0 ( $\pm 1.0$ ) volts between 0 tap and .06 tap

$M_B$  Taps — Use test connection No. 2 and repeat above.

$M_C$  Taps — Use test connection No. 3 and repeat above.

$M_0$  Taps — Use test connection No. 4 and repeat above.

#### For .2 - 4.35 ohm relay

**NOTE: Provide a jumper from terminal 19 to center tap of the  $T_0$  tap block for the SDG-1T relay.**

$M_A$  taps — Use connection No. 1 of Figure 9. Pass 20 amp. of current through relay. The voltages should read as follows:

.425 ( $\pm 0.05$  volts) between "0" tap and ".03" tap

1.70 ( $\pm 0.1$  volts) between "0" tap and ".09" tap

2.55 ( $\pm 0.1$  volts) between "0" tap and ".06" tap

$M_B$  Taps — Use test connection No. 2 and repeat above.

$M_C$  Taps — Use test connection No. 3 and repeat above.

### Part E — Overcurrent Detector (For SDG-1T)

1. Energize dc circuit with rated dc voltage.
2. Use test connection No. 5. Set  $V_{AN} = 0$ ,  $V_{BN} = V_{CN} = 70$  volts. Set current for 0.4 ampere for 1 - 30 ohm relays, and for 0.8 ampere for .2 - 4.35 ohm relays.

Check relay output at test point 12 with voltmeter or oscilloscope. There should be a continuous output of 18-22 volt level under conditions specified above. Adjust R63 potentiometer for specified pickup current. Dropout should occur at:

.38 to .3 amp for 1-30 ohm relays

.76 to .6 amp for .2-4.35 ohm relays

### Part F — Magnitude Comparator Circuit Adjustment (large Printed Circuit Board) — All relays R33 Adjustment

Energize relay with dc only. Connect 10K resistor ( $\pm 5\%$ ) between TP1 of the large PC board and relay terminal 2. Use scope to monitor TP9 and adjust R33 until a positive output is obtained at TP9 (17 - 23 volts).

## Frequency Verifier Adjustment (For SDG-1T-2T)

Use oscilloscope to observe wave shape at test point TP11. Use test connection No. 5. Set  $V_{AN} = 0$   $V_{BN} = V_{CN} = 70$  volts. Set current for 2.5 amps current lagging voltage by  $75^\circ$ . Adjust R76 until less than 1 volt signal of 5.0 to 5.3 ms duration is followed by a positive pulse (17-23 volts) of approximately 3 ms duration. See Test Point Wave Shape, Figure 15a.

## Impedance Check

Start with 2.5 volts test. Use voltmeter for monitoring the relay output. The first short deflection is positive indication of meeting current limits. Then increase current slightly to see if full 18 volt dc output is obtained. There should be no drop in output to zero volts while current is increased. If the currents are outside the limits for 2.5 volt-test as outlined, proceed as follows:

Set  $V_{AN} = V_{BN} = V_{CN} = 70$  volts as close to each other as possible. Use connection No. 5. No current is applied. Measure dc voltage across R9, R10, R11 resistors. Readjust potentiometers R5, R6, R7 until the voltages across R9, R10, R11 are as close to each other as possible. These voltages should be in 20-25 volts range. In most cases only slight adjustment of R5, R6, or R7 will be required. Then recheck pickup current for 2.5 volt test again. If the pickup currents are close together but outside the specified limits readjust R18 or R8 to move all pickup values up or down. Note that R5, R6, R7 are interacting. Therefore, recheck all three voltages after each adjustment. If difficulties in balancing at 2.5 volts persist, use 5 volts and double the limits. If it is desired to check relay response at some other settings use following equation for the trip value of current.

$$I = \frac{3V_{LN}}{(2+p)Z_1}, \text{ where } p = \frac{Z_0}{Z_1}$$

$Z_0$  = Zero sequence reach

$Z_1$  = Positive sequence reach (in above cases  $p = 3$ )

$V_{LN}$  = Faulted Phase Voltage

### 7.1. 1 – 30 Ohm Relay

#### 7.1.1. SDG-1T, SDG-2T, and SDG-4T Relays

Using previous relay tap settings, apply rated dc voltage and proceed as follows:

## Part A: 2.5 VOLT TEST

### Phase A

Use test connection No. 5. Set  $V_{AN} = 2.5$  volts.  $V_{BN} = V_{CN} = 70$  volts. Disable overcurrent unit by jumping terminals 1 & 17 on magnitude comparator module. Adjust R18 for proper pickup level. Pickup current  $I_A$  should be .140 - .155 amps, current lagging voltage  $V_{AN}$  by  $75^\circ$ .

### Phase B

Use test connection No. 6. Set  $V_{BN} = 2.5$  volts.  $V_{AN} = V_{CN} = 70$  volts. Pickup current  $I_B$  should be .140 - .155 amps, current lagging voltage  $V_{BN}$  by  $75^\circ$ .

### Phase C

Use test connection No. 7. Set  $V_{CN} = 10$  volts.  $V_{AN} = V_{BN} = 70$  volts. Pickup current  $I_C$  should be .140 - .155 amps, current lagging voltage  $V_{CN}$  by  $75^\circ$ . Remove jumper from overcurrent unit and return all "S" connections to S=1.

## Part B: 70 VOLTS TEST

### Phase A

Use connections for Test No. 5 and set  $V_{AN} = V_{BN} = V_{CN} = 70$  volts. Set phase-shifter for  $75^\circ$  current lagging voltage. The relay trip current should be 3.95 - 4.20 amperes, current lagging voltage  $V_{AN}$  by  $75^\circ$ .

### Phase B

Use connections for Test No. 6 and set  $V_{AN} = V_{BN} = V_{CN} = 70$  volts, and set the phase-shifter as above. The relay trip current should be 3.95 - 4.20 amperes, lagging  $75^\circ$   $V_{CN}$  voltage.

### Phase C

Use test connections for Test No. 7 and set  $V_{AN} = V_{BN} = V_{CN} = 70$  volts. Set the phase-shifter as above. The relay trip current should be 3.95 - 4.20 amperes, current lagging  $75^\circ$  voltage  $V_{CN}$  by  $75^\circ$ .

## Part C: S = 3 TEST

Set  $S_A, S_B, S_C = 3$ . Set  $V_{BN} = V_{CN} = 70$  volts.  $V_{AN} = 10$  volts. Disable overcurrent unit again as for 2.5 volt test.

### Phase A

Use test connection No. 5. Pickup Current  $I_A$  should be .190 -.218 amps, current lagging voltage  $V_{AN}$  by  $75^\circ$ .

### Phase B

Use test connection No. 6. Set  $V_{BN} = 10$  volts.  $V_{AN} = V_{CN} = 70$  volts. Pickup current  $I_B$  should be .190 -.218 amps, current lagging voltage  $V_{BN}$  by  $75^\circ$ .

### Phase C

Use test connection No. 7. Set  $V_{CN} = 10$  volts.  $V_{AN} = V_{BN} = 70$  volts. Pickup current  $I_C$  should be .190 -.218 amps, current lagging voltage  $V_{CN}$  by  $75^\circ$ . Remove jumper from overcurrent unit and return all "S" connections to  $S = 1$ .

## **7.2. .2 – 4.25 Ohm Relay**

### **7.2.1. SDG-1T, SDG-2T, SDG-4T Relays**

Using previous relay tap settings, apply rated dc voltage and proceed as follows.

### **Part A: 2.5 VOLT TEST**

#### Phase A

Use test connection No. 5. Set  $V_{AN} = 2.5$  volts.  $V_{BN} = V_{CN} = 70$  volts. Disable overcurrent unit by jumping terminals 1 & 17 on magnitude comparator module. Adjust R18 for proper pickup level. Pickup current  $I_A$  should be 1.00 - 1.10 amps, current lagging voltage  $V_{AN}$  by  $75^\circ$ .

#### Phase B

Use test connection No. 6. Set  $V_{BN} = 2.5$  volts,  $V_{AN} = V_{CN} = 70$  volts. Pickup current  $I_B$  should be 1.00 - 1.10 amps, current lagging voltage  $75^\circ$ .

#### Phase C

Use test connection No. 7. Set  $V_{CN} = 2.5$  volts,  $V_{AN} = V_{BN} = 70$  volts. Pickup current should be 1.00 - 1.10 amps, current lagging voltage  $V_{CN}$  by  $75^\circ$ . Remove jumper from overcurrent unit and return all "S" connections to  $S = 1$ .

If limits above are not met, see special note under "Impedance Test."

### **Part B: 20 VOLT TEST**

#### Phase A

Use test connection No. 5. Set  $V_{AN} = 20$  volts.  $V_{BN} = V_{CN} = 70$  volts. Set phase-shifter for  $75^\circ$  current lagging voltage. Pickup current  $I_A$  should be 8.05 - 8.55 amps, current lagging  $V_{AN}$  voltage by  $75^\circ$ .

#### Phase B

Set  $V_{BN} = 20$  volts,  $V_{AN} = V_{CN} = 70$  volts. Use test connection No. 6. Pickup current  $I_B$  should be 8.05 - 8.55 amp, current lagging  $V_{BN}$  voltage by  $75^\circ$ .

#### Phase C

Set  $V_{CN} = 20$  volts,  $V_{AN} = V_{BN} = 70$  volts. Use test connection No. 6. Pickup current  $I_C$  should be 8.05 - 8.55 amps, current lagging  $V_{CN}$  voltage by  $75^\circ$ .

### **Part C: S = 3 TEST**

Set  $S_A = S_B = S_C = 3$ . Set  $V_{AN} = 10$  volts.  $V_{BN} = V_{CN} = 70$  volts.

#### Phase A

Use test connection No. 5. Pickup current  $I_A$  should be 1.35 - 1.43 amps, current lagging voltage  $V_{AN}$  by  $75^\circ$ .

#### Phase B

Use test connection No. 6. Set  $V_{BN} = 10$  volts,  $V_{AN} = V_{CN} = 70$  volts. Pickup current  $I_B$  should be 1.35 - 1.43 amps, current lagging voltage  $V_{BN}$  by  $75^\circ$ .

#### Phase C

Use test connection No. 7. Set  $V_{CN} = 10$  volts,  $V_{AN} = V_{BN} = 70$  volts. Pickup current  $I_C$  should be 1.35 - 1.43 amps, current lagging voltage  $V_{CN}$  by  $75^\circ$ . Remove jumper from overcurrent unit and return all "S" connections to  $S = 1$ .

### **7.3. push-button Test**

Use test connection No. 1. No current is required. Apply dc to the relay. Open circuit voltage connection to relay terminal No. 7. Set  $V_{BN} = V_{CN} = 70$  volts. Depress white push-button and it should light.

#### **7.3.1. Indicating Contactor Switch**

With the relay tripped, pass sufficient dc current through the trip circuit to close the contacts of ICS. This value of current should be not less than 1.0

ampere, nor greater than 1.2 amperes for the 1 ampere ICS. The current should not be greater than the particular ICS setting being used for the 0.2-2.0 amperes ICS. The operation indicator target should drop freely.

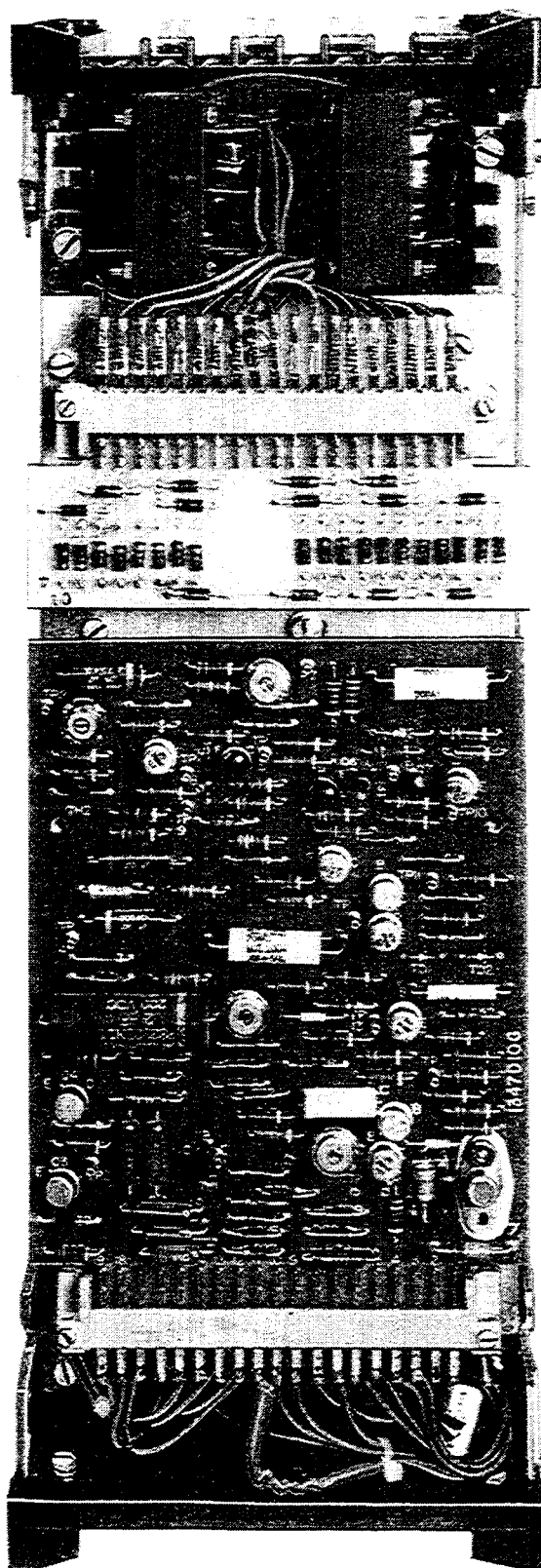
The contact gap should be approximately 0.047" for the 0.2-2.0 ampere unit and 0.070" for the 1.0 ampere unit between the bridging moving contact and the adjustable stationary contacts. The bridging moving contact should touch both stationary contacts simultaneously.

## 8. RENEWAL PARTS

Repair work can be done most satisfactorily at the factory. However, interchangeable parts can be furnished to the customers who are equipped for doing repair work. When ordering parts, always give the complete nameplate data, and component style number given in the electrical parts list.

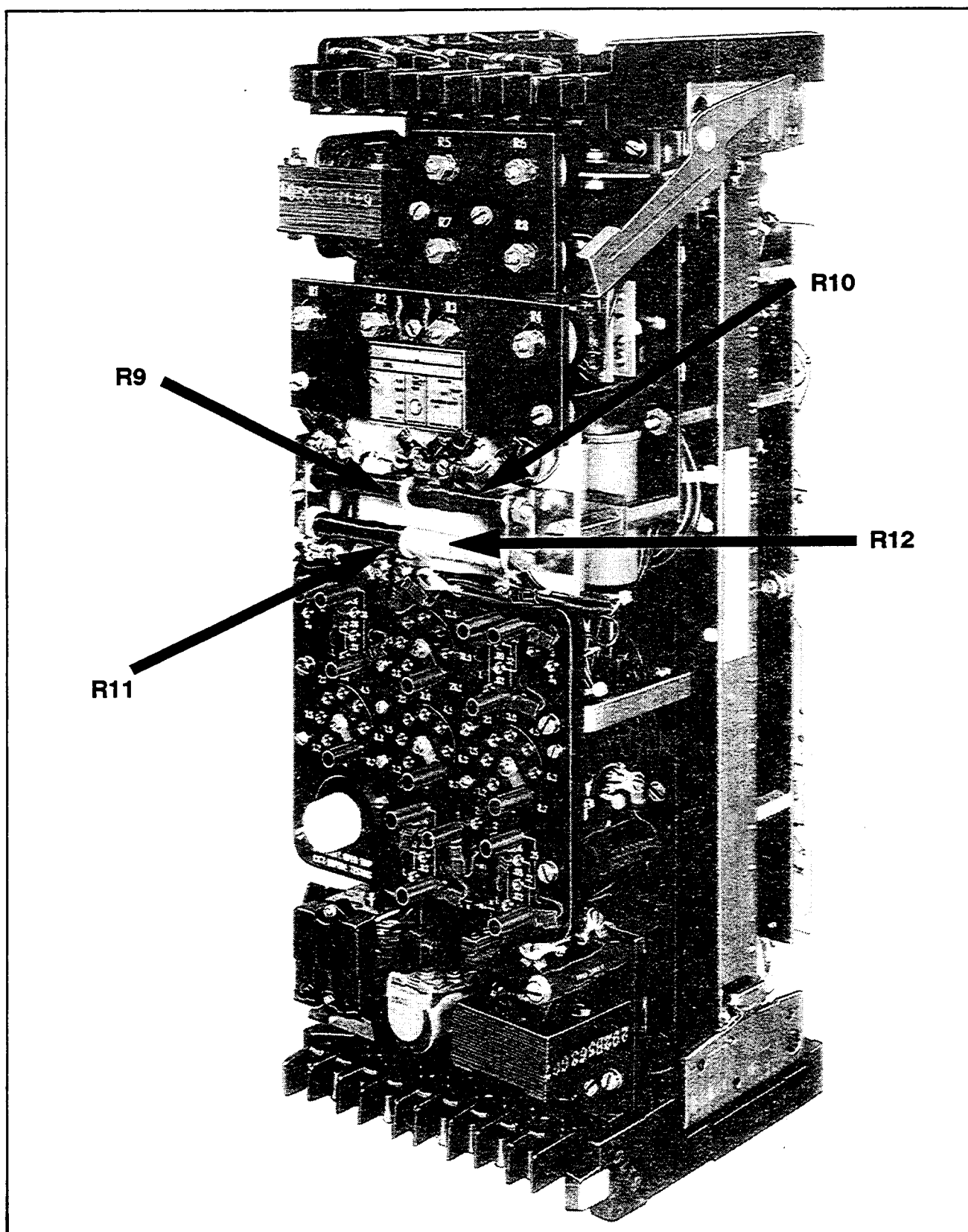
See detailed Internal Schematics for printed circuit styles and Reference Drawing list for component location details.

Figure	Description	Drawing
1	SDG-1T Relay without Case (Front View)	PHOTO
2	SDG-1T Relay without Case (Rear View)	PHOTO
3	SDG-2T Relay without Case (Front View)	PHOTO
4	SDG-2T Relay without Case (Rear View)	PHOTO
5	Detailed Internal Schematic of SDG-1T Relay with Parts List	6694D74
6	Internal Diagram of Type SDG-2T	719B766
7	Detailed Internal Schematic of SDG-2T Relay with Parts List	6694D77
8	SDG-4T Detailed Internal Schematic Relay with Parts List (Double Contact)	1339D60
9	Test Connections for SDGT Line	1495B95
10	Typical Operating Time Curves	9646A38
11	Distance Phase and Distance Ground Relaying (External Connections)	2396F25
12	Outline and Drilling Plan for SDGT Line Relays in an FT-42 Case	57D7905
13	Compensator Construction	849A034
14	Impedance Circles for the SDG Line Relays	837A14, 15, 16
15	Test Points for SDGT – Line of Relays	9646A39
15a	Test Points for SDGT – Line of Relays	9646A40
16	Definition of Terms	837A125
17	Fault Resistance	837A125
18	Relay Voltages for AG Faults at Selected Points	837A117
19	Impedance Curve for the SDGT Line of Relays	878A006
20	SDGT-1T Component Location of Magnitude Comparator Board	774B971
21	SDGT-2T Component Location of Magnitude Comparator Board	774B972
22	SDGT-4T Component Location	203C301
23	SDG-1T-2T-4T component Location of Phase Splitter Rectifier Board	716B095
24	SDG-1T and SDG-2T 2 $\phi$ -Ground Board Parts Component Location	774B966
25	SDG-1T Capacitor – Restraint Filter Board – Parts Location	3507A85
26	SDG-2T Capacitor – Restraint Filter Board – Parts Location	3507A86

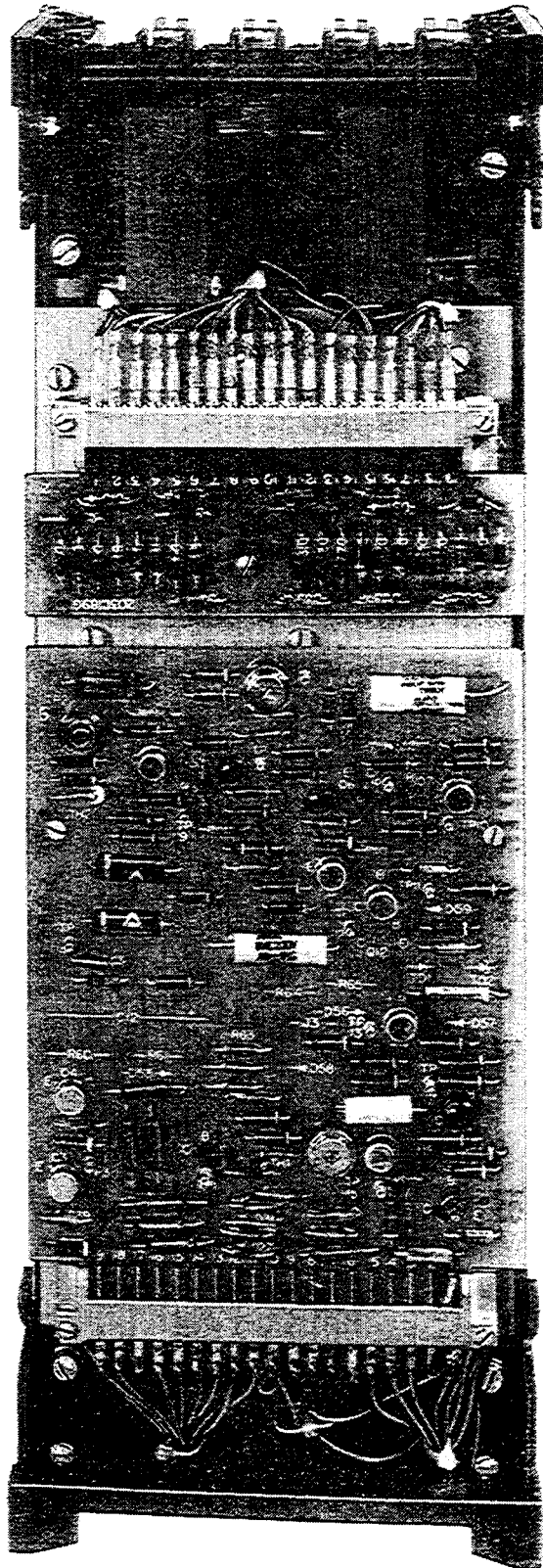


★ Fig. 2. Type SDG-1T Relay Without Case (Rear View)

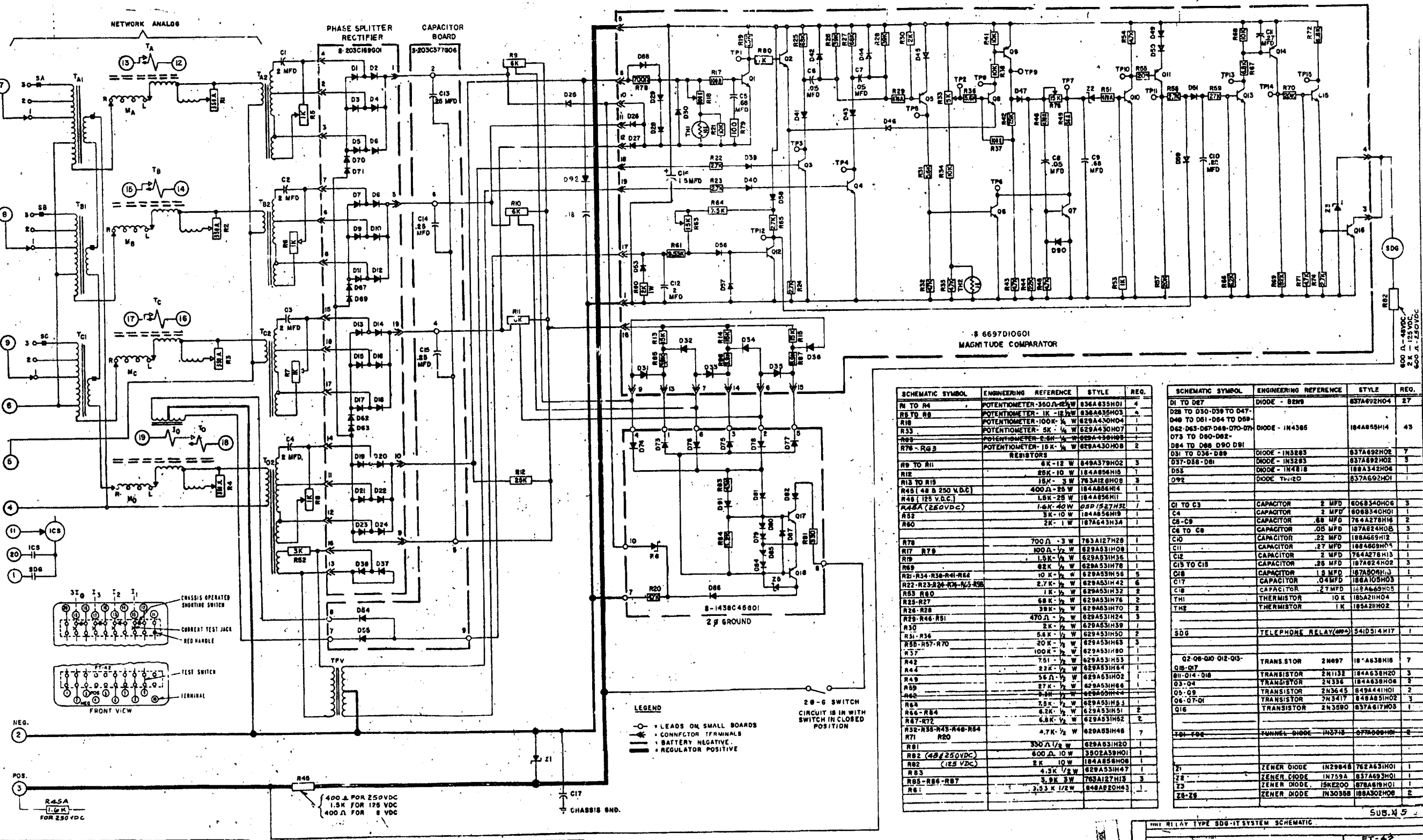




★ Fig. 3. Type SDG-2T Relay Without Case (Front View)



• Fig. 4. Type SDG-2T Relay Without Case (Rear View)



SO 1  
D-774259  
RC 2  
APPR. NAME WAS  
SDGT-1  
V.B. 9-13-72  
R.C. 9-13-72

T<sub>0</sub> COMPENSATOR  
PRIMARY  
T<sub>C</sub> COMPENSATOR  
PRIMARY  
T<sub>A</sub> COMPENSATOR  
T<sub>B</sub> PRIMARY

AC 3  
APPR. NAME WAS  
SDG-IT. K.S. 9/26/72  
R.C. 9-26-72  
DESIGNATION IS TB IA  
WERE I<sub>3</sub> I<sub>2</sub> I<sub>1</sub> RESA  
NEUTRAL PHA PHB PHC W  
WERE PH1 PH2 PH3  
A. 10-2-72 TB/SS 10/4/72

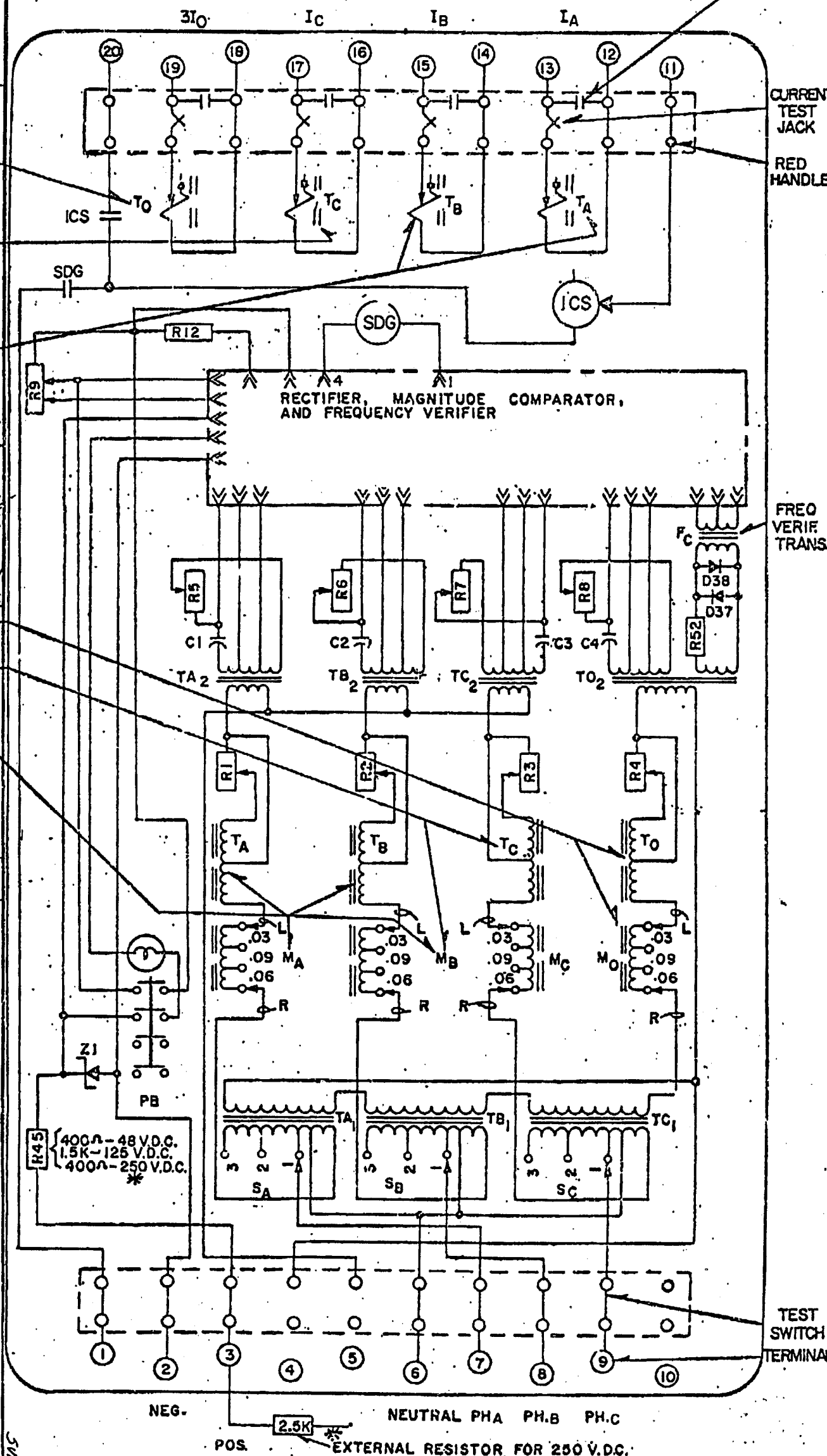
T<sub>0</sub> COMPENSATOR  
SECONDARY  
T<sub>C</sub> COMPENSATOR  
SECONDARY  
T<sub>A</sub> COMPENSATOR  
T<sub>S</sub> SECONDARY

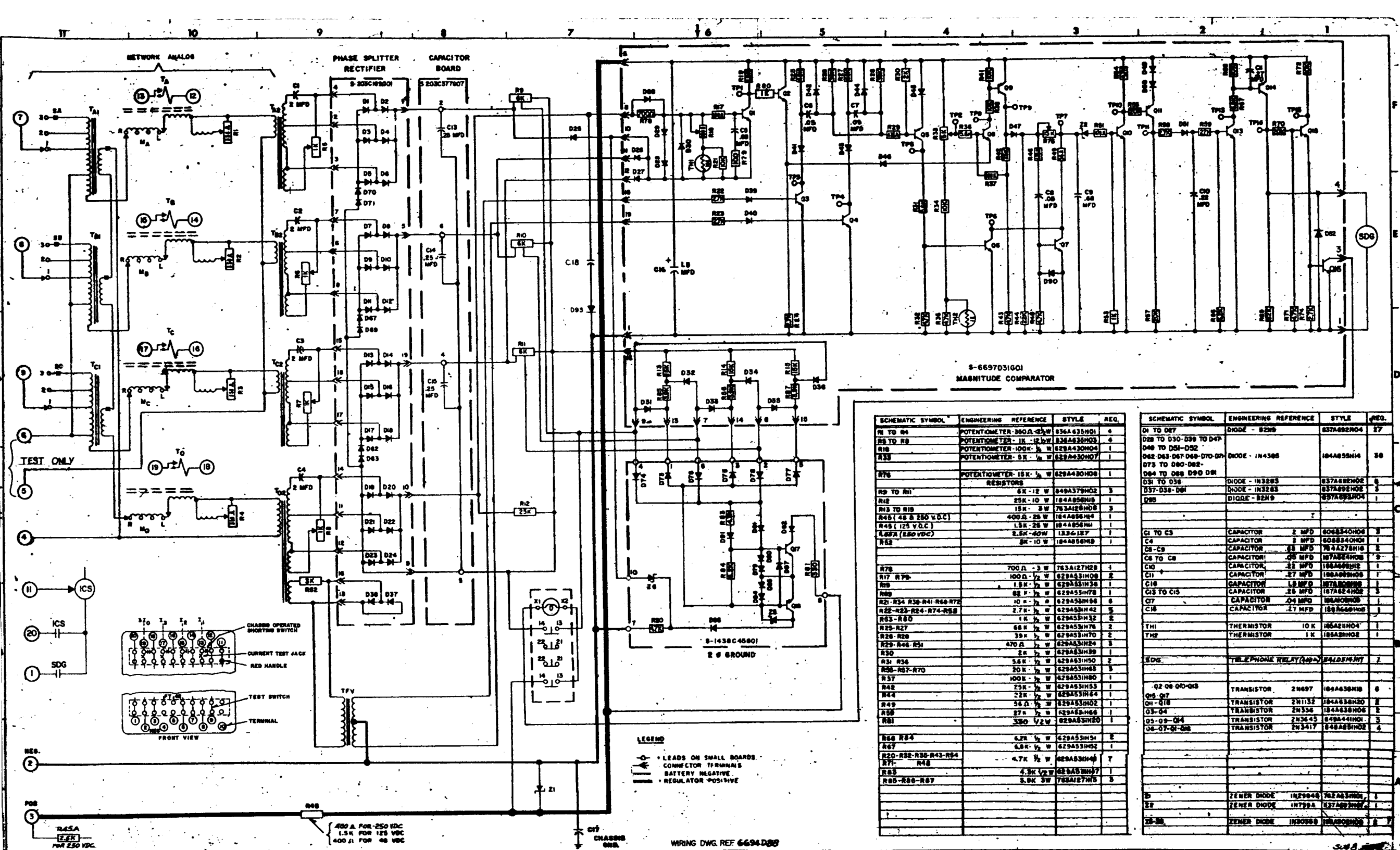
ENGR. REF. DWG. 6708238

TITLE			
Westinghouse Electric Corporation			
RELAY TYPE SDG-2T INTERNAL SCHEMATIC			
CHKR.	DATE	APPROV.	DWG. NO.
CH	7/72	CH	719B766
APPD		APPD	
SHEET			
OF			
CON			

RELAY TYPE SDG-2T  
GROUND DISTANCE TYPE  
IN FT-42 CASE  
INTERNAL SCHEMATIC

CHASSIS OPERATED  
SHORTING SWITCH





SCHEMATIC SYMBOL	ENGINEERING REFERENCE	STYLE	REQ.
R1 TO R4	POTENTIOMETER - 500Ω - 1/2 W	636A435H01	4
R5 TO R8	POTENTIOMETER - 1K - 1/2 W	636A435H03	4
R9	POTENTIOMETER - 100K - 1/2 W	629A430H04	1
R33	POTENTIOMETER - 5K - 1/2 W	629A430H07	1
R76	POTENTIOMETER - 15K - 1/2 W	629A430H08	1
R89 TO R91	RESISTORS		
R9	5K - 1/2 W	640A375H02	3
R2	25K - 1/2 W	184A655H01	1
R15 TO R18	15K - 1/2 W	763A125H03	3
R46 (48 & 250 V.D.C.)	400Ω - 20 W	184A655H04	1
R45 (125 V.D.C.)	15K - 20 W	184A655H04	1
R52	2.5K - 40W	133A-157	1
R52	5K - 10 W	184A655H05	1
R78	700Ω - 3 W	763A127H02	1
R17 R79	100Ω - 1/2 W	629A531H02	2
R8	15K - 1/2 W	629A531H04	1
R89	82 K - 1/2 W	629A531H78	1
R21 R34 R36 R41 R60 R72	10 K - 1/2 W	629A531H06	6
R22 R23 R24 R74 R85	2.7K - 1/2 W	629A531H42	5
R35 R80	1K - 1/2 W	629A531H32	2
R25 R27	68K - 1/2 W	629A531H76	2
R26 R28	39K - 1/2 W	629A531H70	2
R29 R48 R51	470Ω - 1/2 W	629A531H24	3
R30	2K - 1/2 W	629A531H39	1
R31 R36	5.6K - 1/2 W	629A531H50	2
R56 R57 R70	20K - 1/2 W	629A531H83	3
R37	100K - 1/2 W	629A531H80	1
R42	25K - 1/2 W	629A531H53	1
R44	22K - 1/2 W	629A531H64	1
R49	56Ω - 1/2 W	629A531H02	1
R50	27Ω - 1/2 W	629A531H66	1
R81	330 - 1/2 W	629A531H20	1
R66 R64	62K 1/2 W	629A531H51	2
R67	6.8K 1/2 W	629A531H52	1
R20 R32 R35 R43 R64	4.7K 1/2 W	629A531H46	7
R71 R48			
R83	4.3K 1/2 W	629A531H57	1
R68 R69 R67	5.9K 5W	763A127H03	3

SCHEMATIC SYMBOL	ENGINEERING REFERENCE	STYLE	REQ.
D1 TO D27	DIODE - 62N9	637A692H04	27
D28 TO D30 D39 TO D47	DIODE - IN4368	184A655H14	50
D48 TO D51 D52	DIODE - IN4368	184A655H14	8
D62 D63 D67 D68 D70 D71	DIODE - IN4368	184A655H14	3
D73 TO D80 D82	DIODE - 62N9	637A692H04	1
D84 TO D88 D90 D91	DIODE - IN4368	184A655H14	8
D93 TO D96	DIODE - IN4368	184A655H14	3
D97 D98 D99	DIODE - 62N9	637A692H04	1
C1 TO C5	CAPACITOR 2 MFD	606A340H08	3
C4	CAPACITOR 2 MFD	606A340H08	1
C6 C9	CAPACITOR .05 MFD	764A275H10	2
C8 TO C8	CAPACITOR .05 MFD	764A275H10	2
C10	CAPACITOR .05 MFD	764A275H10	1
C11	CAPACITOR .05 MFD	764A275H10	1
C16	CAPACITOR 1.5 MFD	184A655H12	1
C15 TO C15	CAPACITOR .25 MFD	184A655H12	3
C17	CAPACITOR .04 MFD	184A655H12	1
C18	CAPACITOR .27 MFD	184A655H12	1
TH1	THERMISTOR 10K	184A655H14	1
TH2	THERMISTOR 1K	184A655H14	1
SDG	TELEPHONE RELAY (100V) 24105H11		1
Q2 Q6 Q10 Q12	TRANSISTOR 2N697	184A655H18	6
Q5 Q7	TRANSISTOR 2N1132	184A655H20	2
Q1 Q18	TRANSISTOR 2N334	184A655H08	2
Q3 Q4	TRANSISTOR 2N3645	184A655H01	3
Q5 Q9 Q14	TRANSISTOR 2N3417	184A655H02	4
Q7 Q1 Q1 Q1	TRANSISTOR 2N3417	184A655H02	4
Z	ZENER DIODE 1N2946	762A635H04	1
Z2	ZENER DIODE 1N2946	762A635H04	1
Z3 Z4	ZENER DIODE 1N2946	762A635H04	2

LEADS ON SMALL BOARDS.  
CONNECTOR TERMINALS  
BATTERY NEGATIVE  
REGULATOR POSITIVE



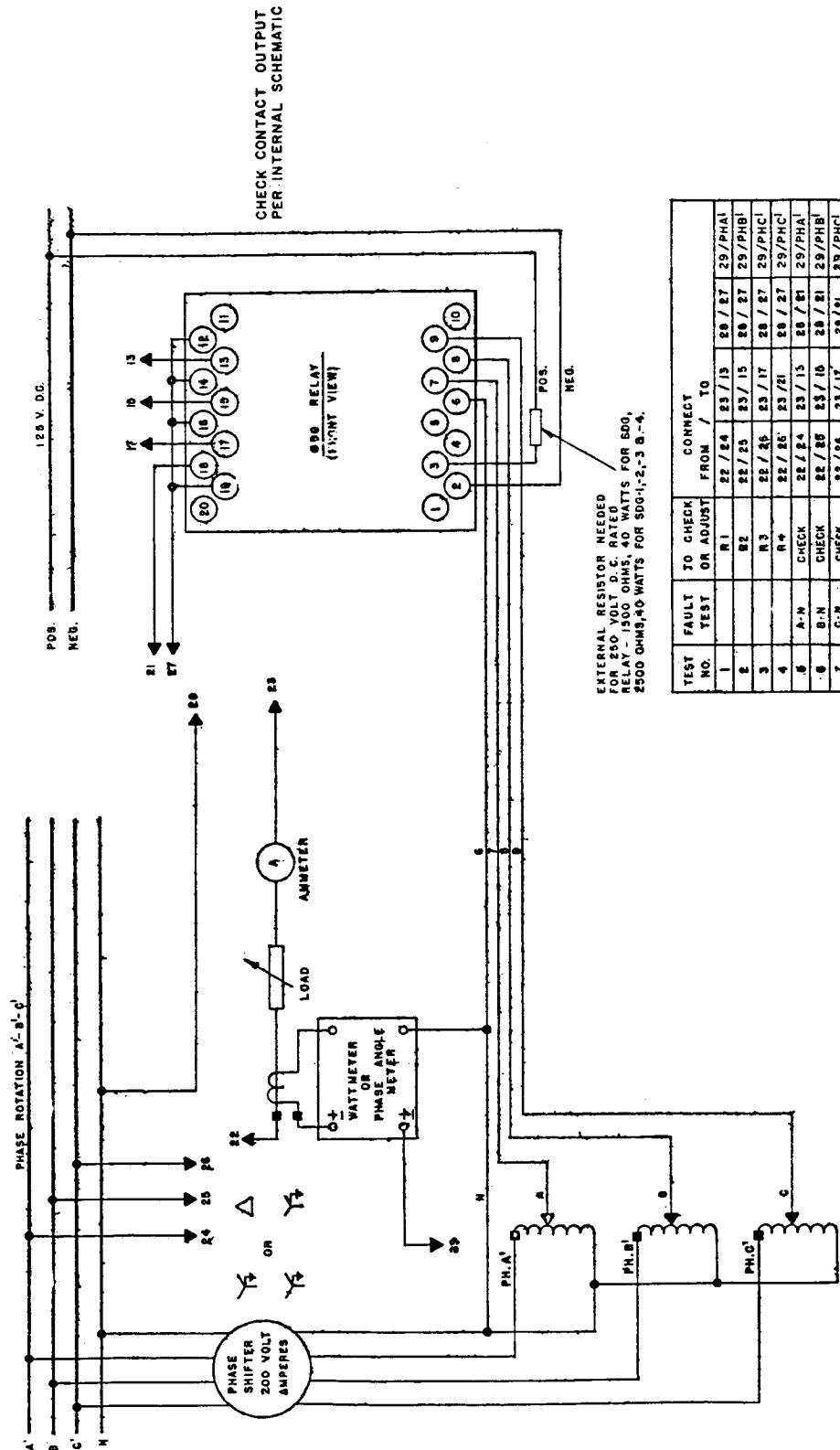
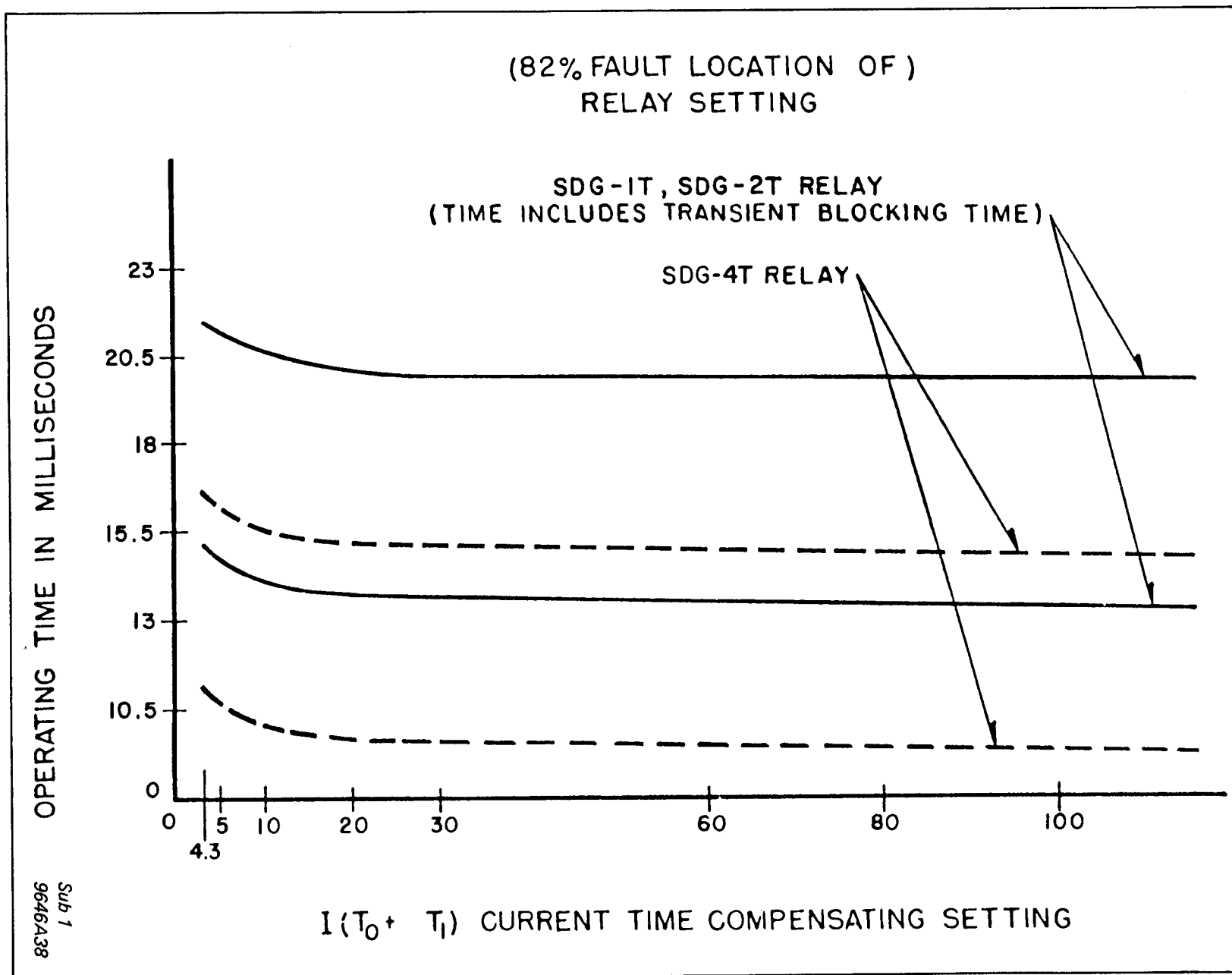


Fig. 9. Test Connections for SDGT Line

Sub 1  
1495B95

Fig. 10. Typical Operating Time Curves







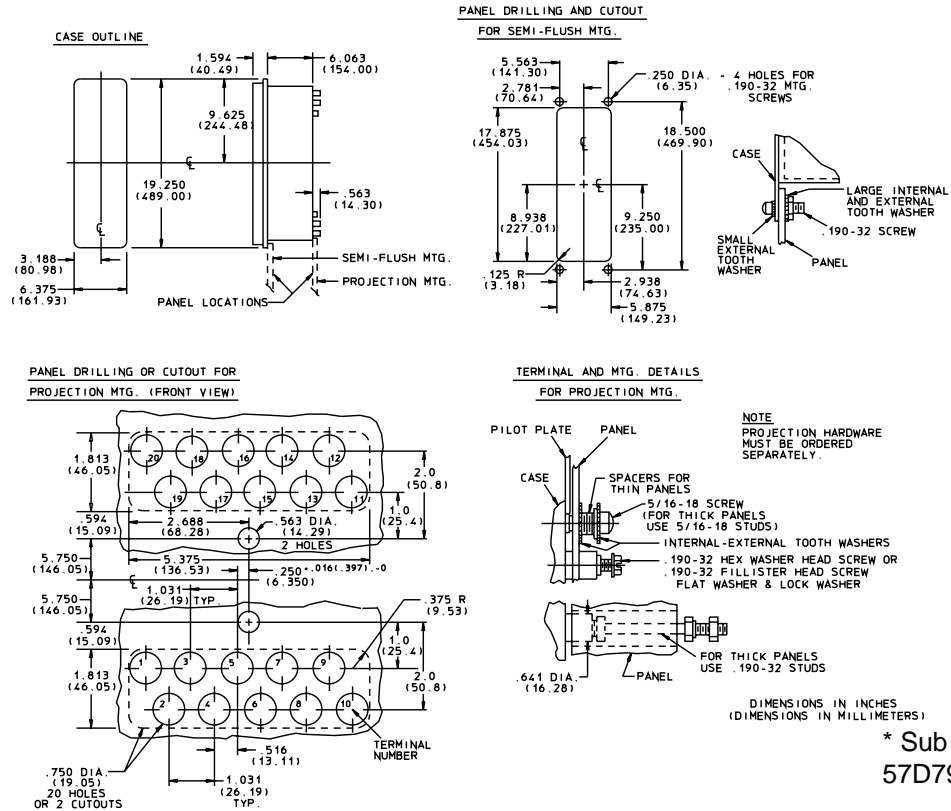


Figure 12. Outline and Drilling Plan for the SDGT Line Relays in an FT-42 Case

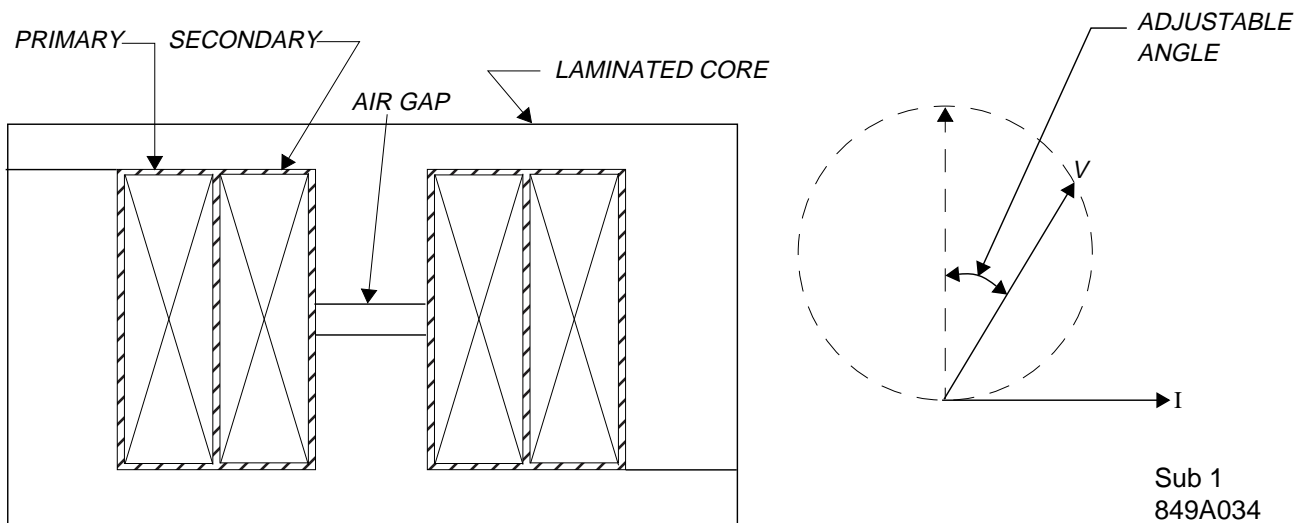
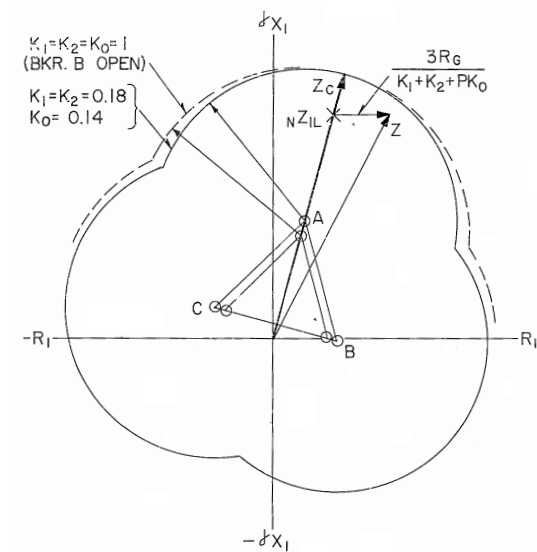
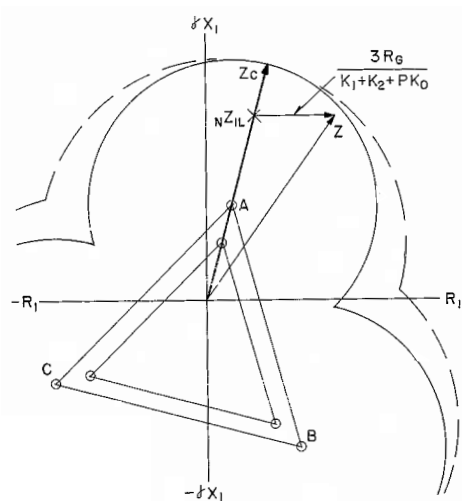


Figure 13. Compensator Construction



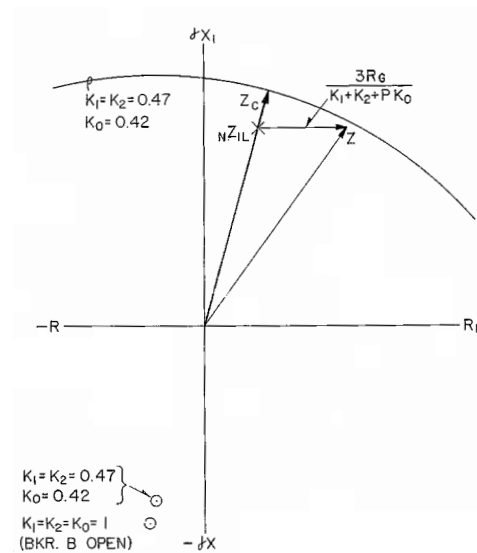
a) Long Line

(A)  
837A116



### b) Medium-Length Line

(B)  
837A114



c) Short Line

(C)  
837A115

Figure 14. Impedance Circles for the SDG Line Relays

SDGT – LINE (.2 TO 4.35Ω)

$$S_{A, B, C} = 1$$

$$T_{A, B, C} = 1.23\Omega; T_O = 3.69\Omega$$

TEST POINT TRACES

$$M_{A, B, C, O} = +.18$$

(D.C. NEG. REF.)

$$V_{A-G} = 2.5VAC;$$

NO TRIP

$$V_{3\phi-G} = 70VAC$$

TRIP

$$V_{B, C-G} = 70VAC$$

$$I_{3\phi-G} = 0$$

$$I_{A-G} = 3AMP$$

SDG-1T	EQUIVALENT TEST POINTS				
		SDG-2T		SDG-4T	
1	—	1	—	1	—
2	—	2	—	2	—
3	—	3	—	—	—
4	—	4	—	—	—
5	—	5	—	—	—
6	—	6	—	6	—
7	—	7	—	7	—
8	—	8	—	8	—
9	—	9	—	9	—
10	—	10	—	10 *	—
11	—	11	—	11 Δ	—
12	—	—	—	—	—
13	—	—	—	—	—
14	—	—	—	—	—
15	—	—	—	—	—

$$* = 0.7 - 7.6 \quad \Delta = 7.6 - 0.7$$

Sub 1  
9646A39

Figure 15. Test Points for SDGT - Line of Relays

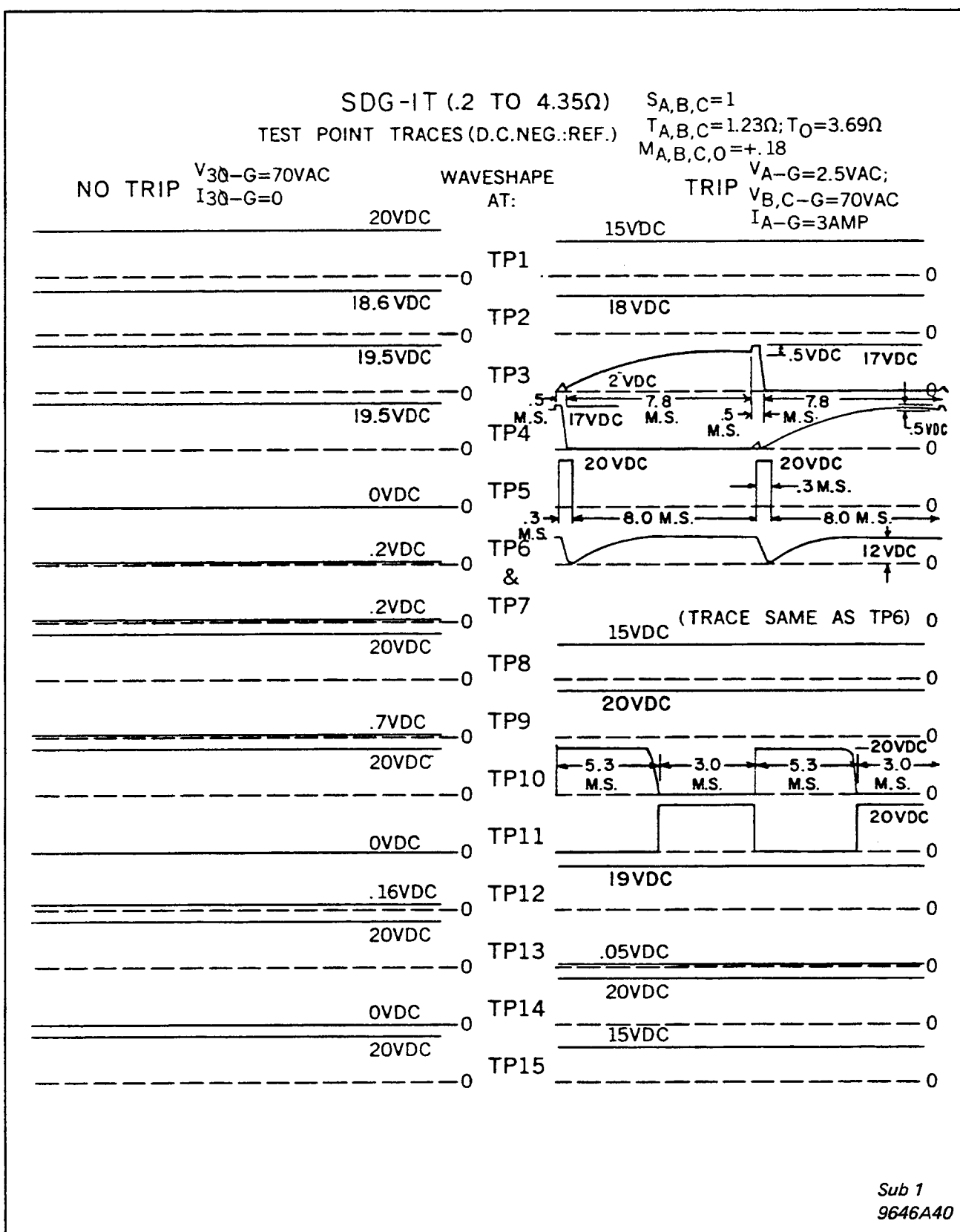
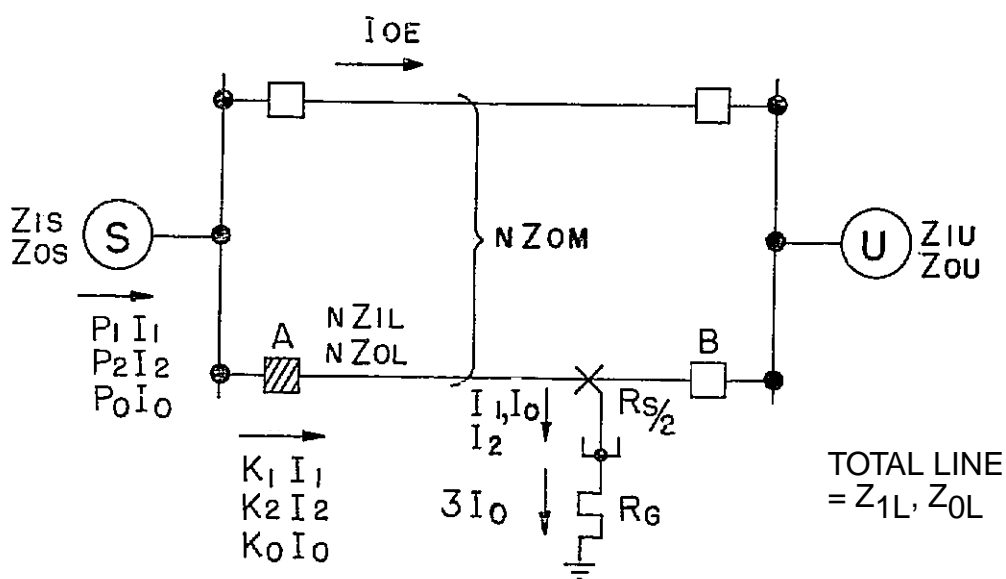
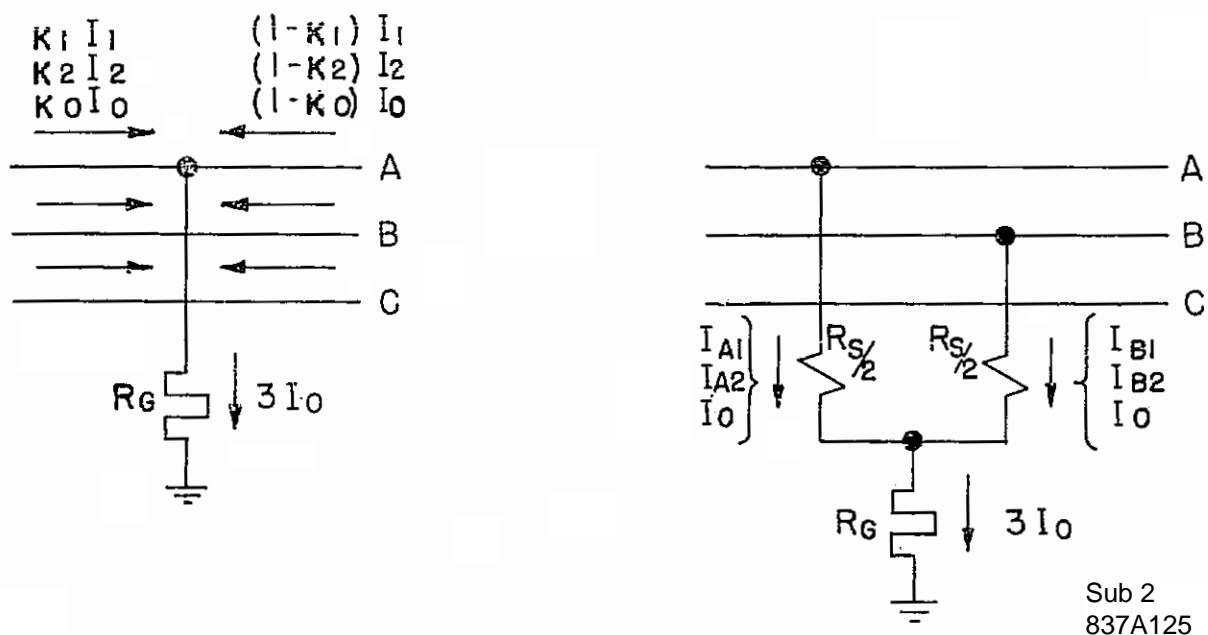


Fig. 15a. Test Points for SDGT - Line of Relays



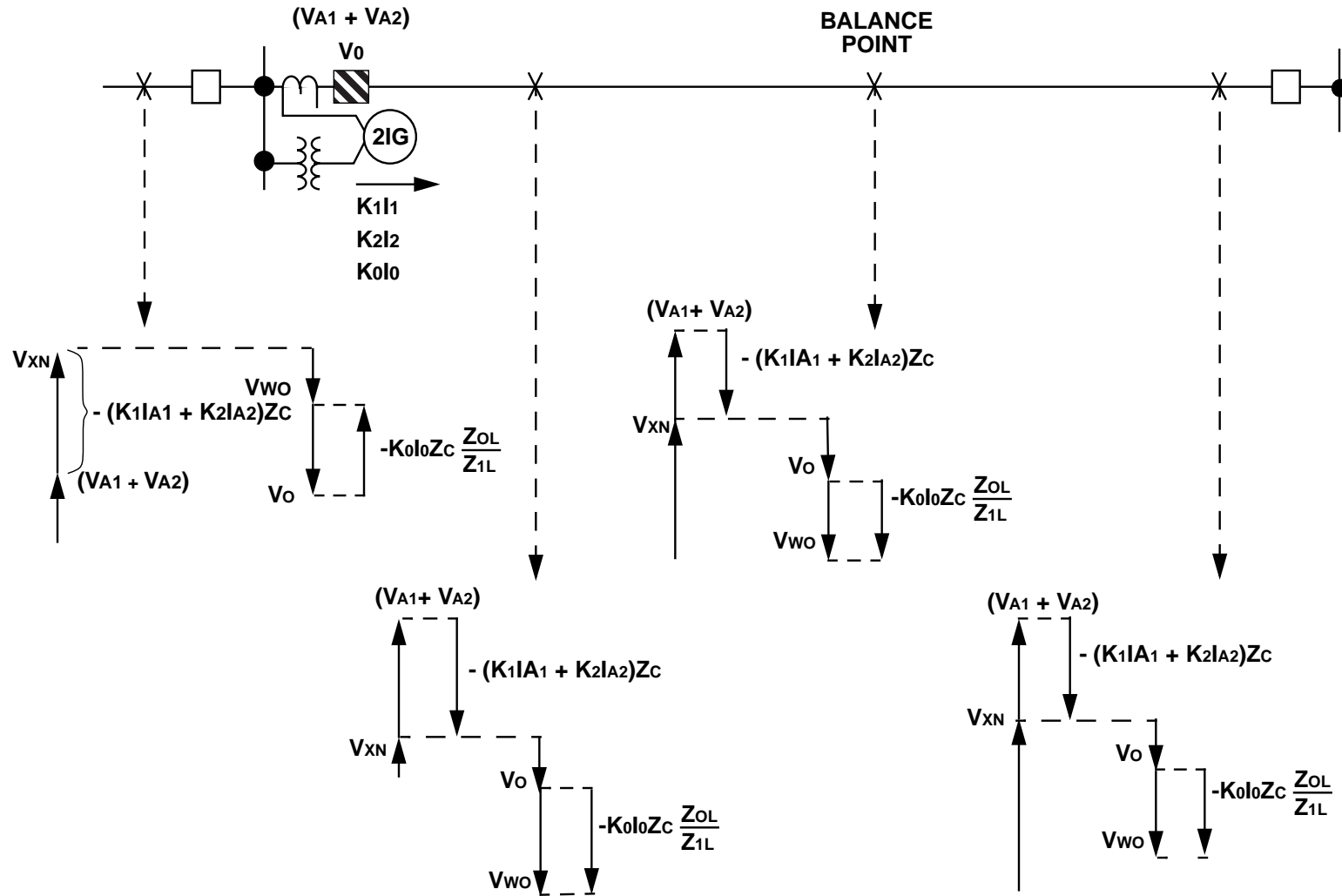
Sub 2  
837A125

Figure 16. Definition of Terms



Sub 2  
837A125

Figure 17. Fault Resistance



Sub 2  
837A117

Figure 18. Relay Voltages for AG to Ground Faults at Selected Points

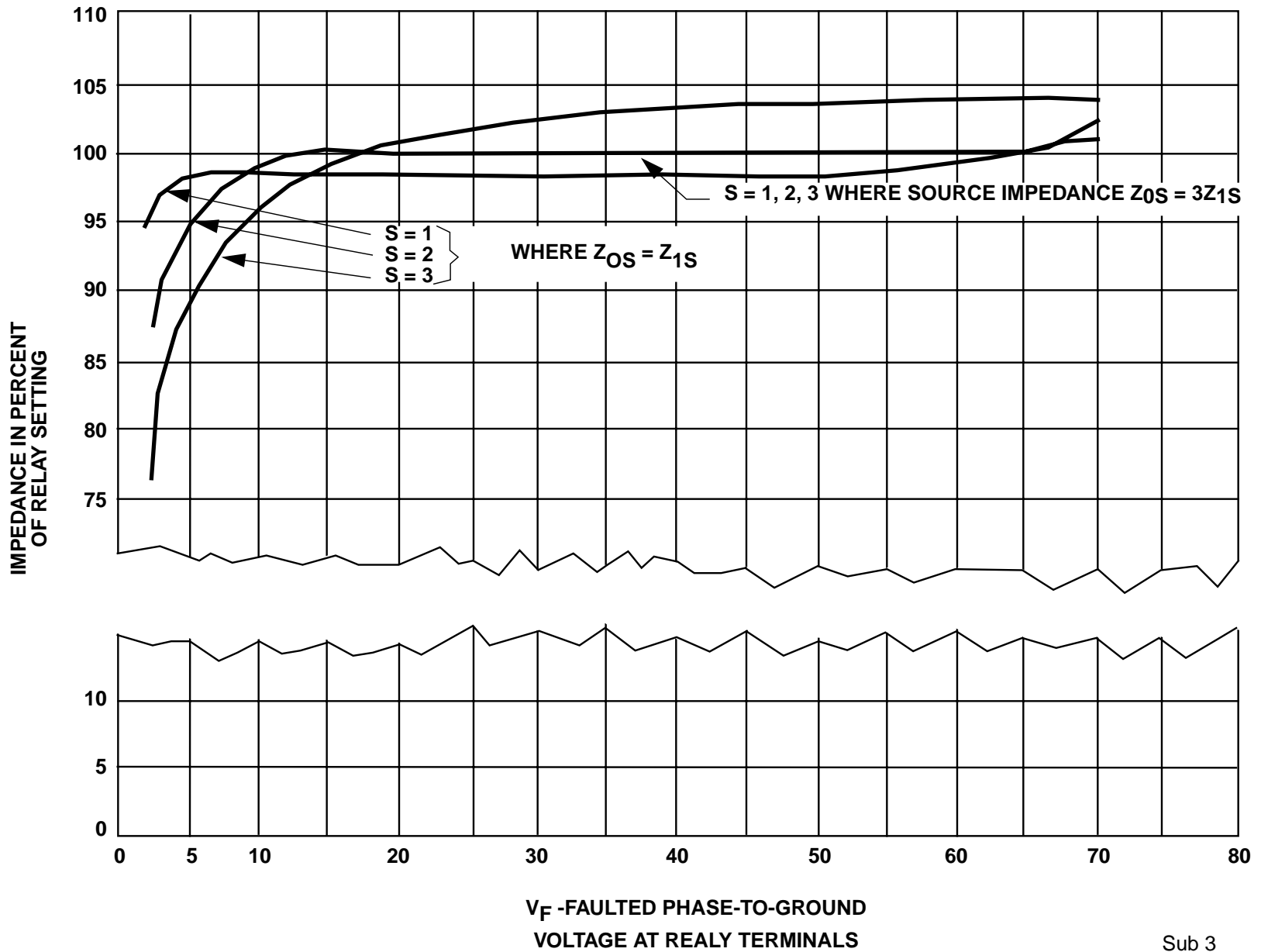
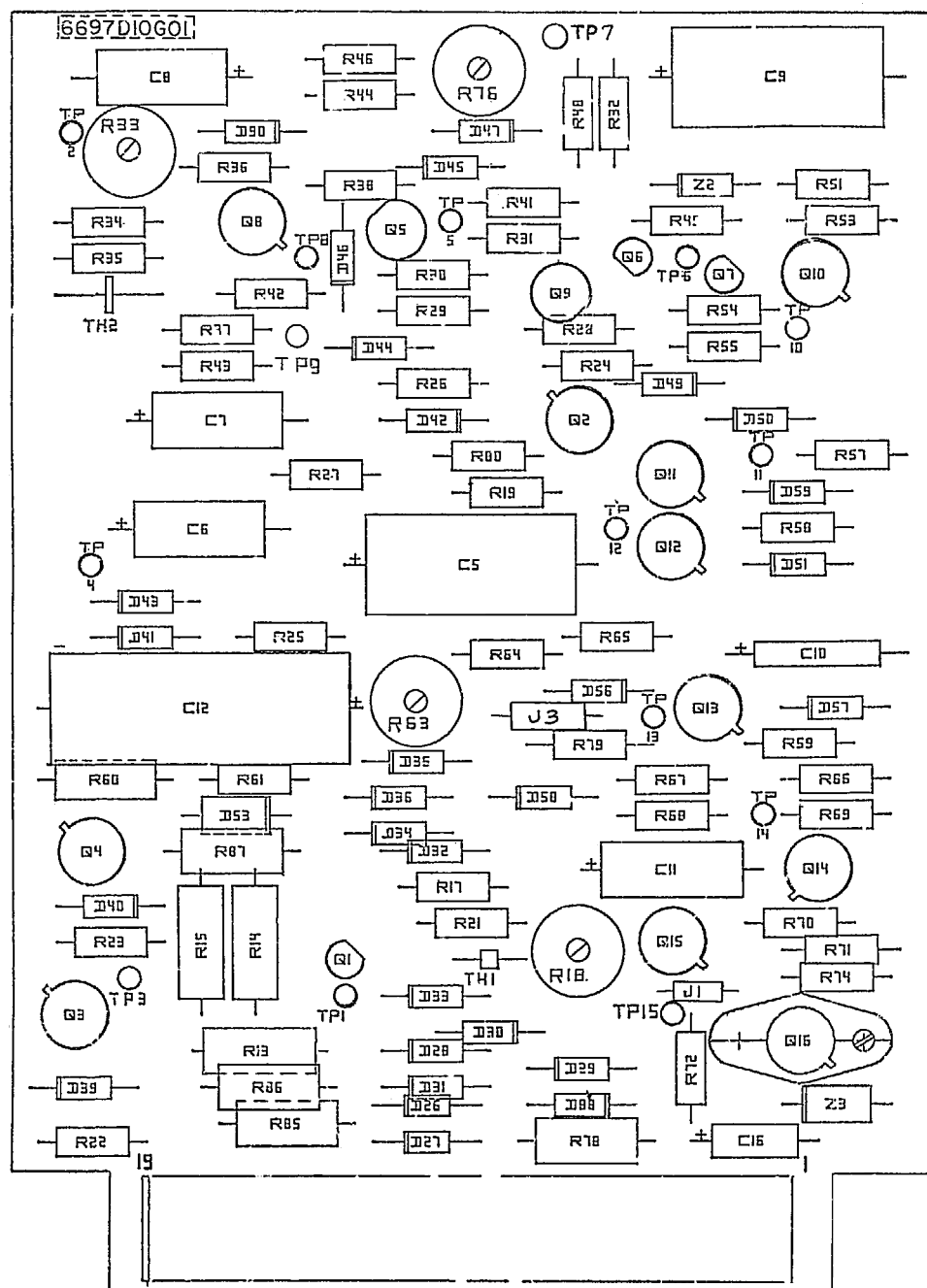


Figure 19. Impedance Curve for the SDGT Line of Relays

Sub 3  
878A006





Sub 2  
774B971

Figure 20. SDG-1T Component Location of Magnitude Comparator Board

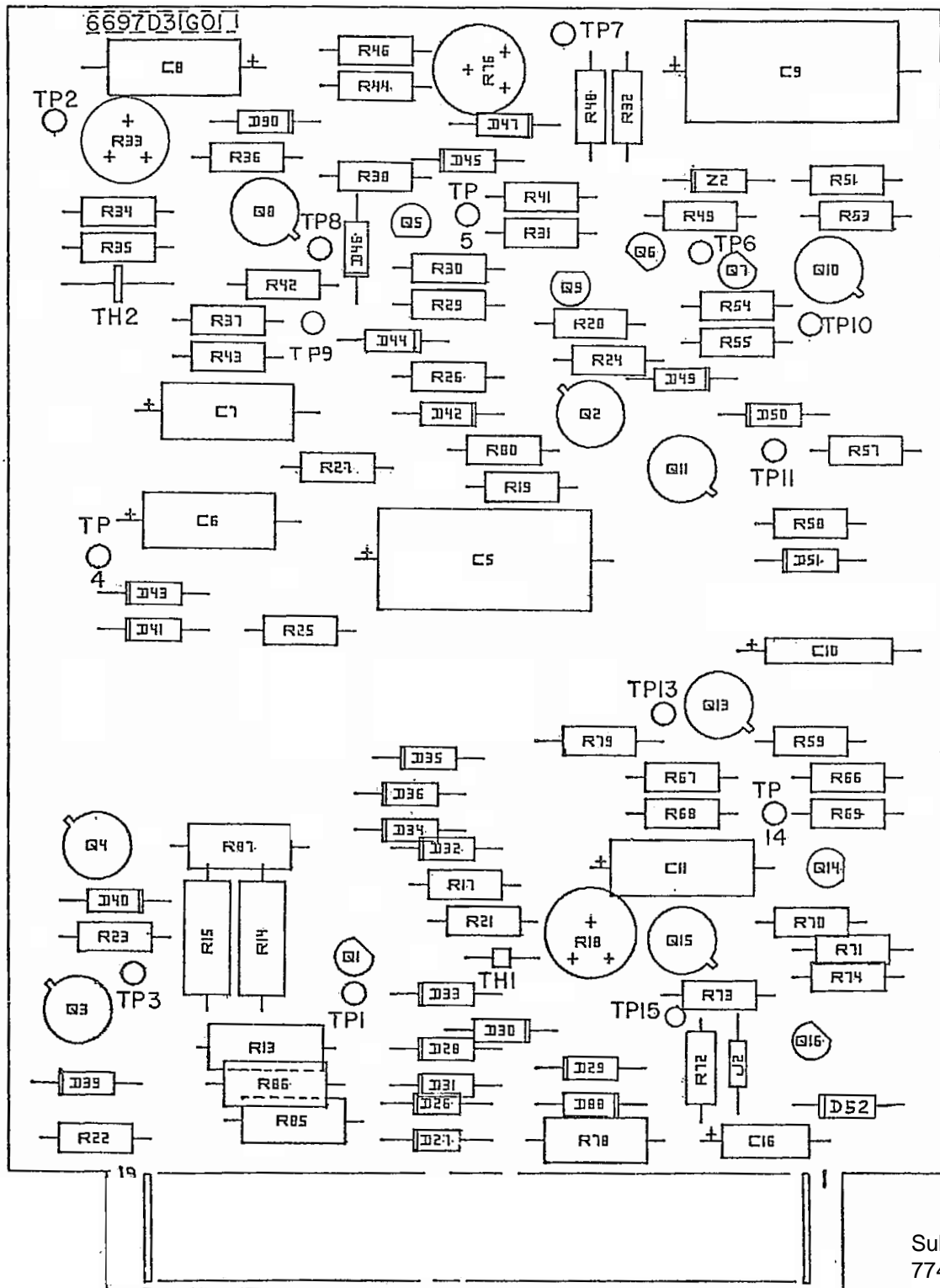
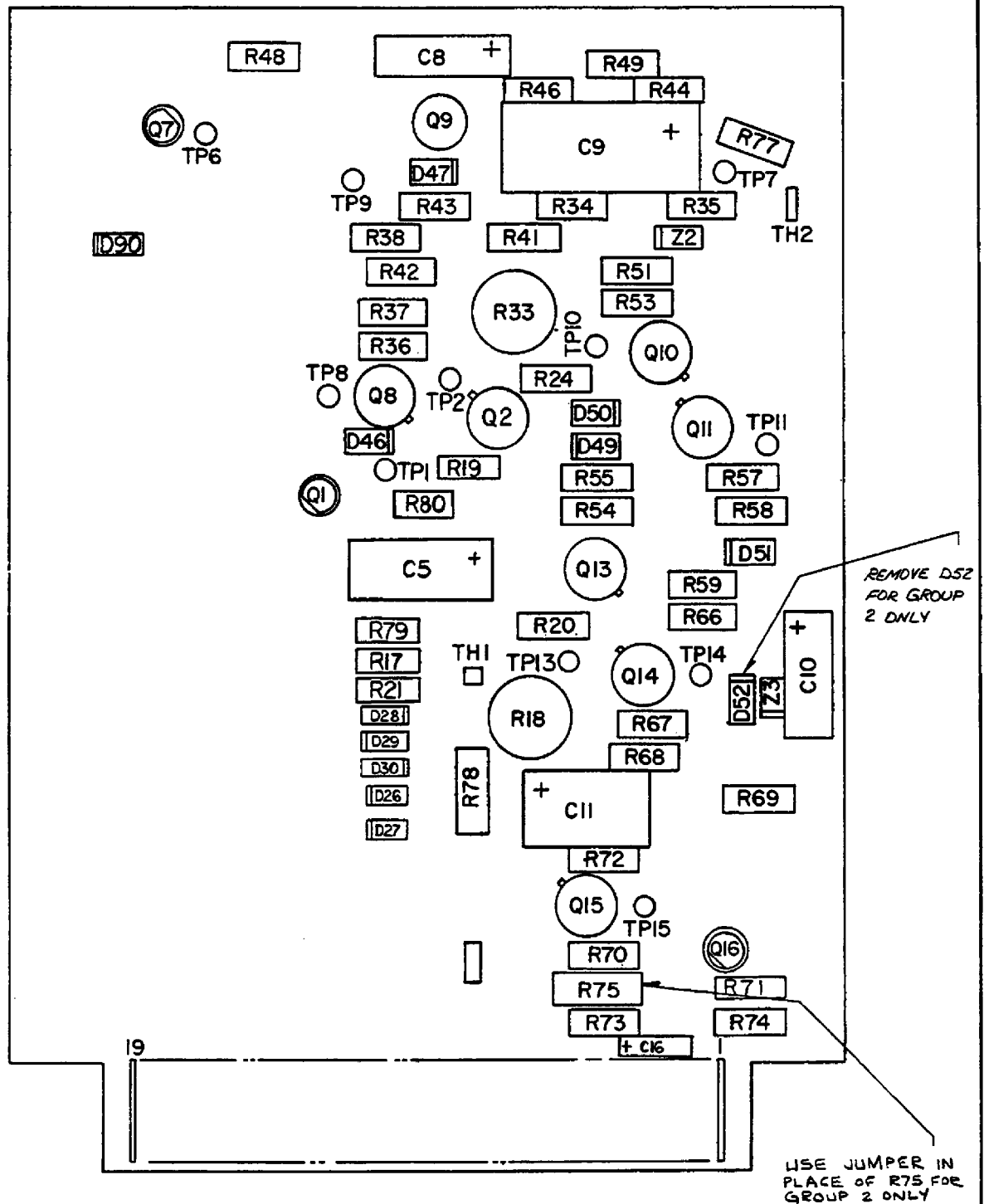


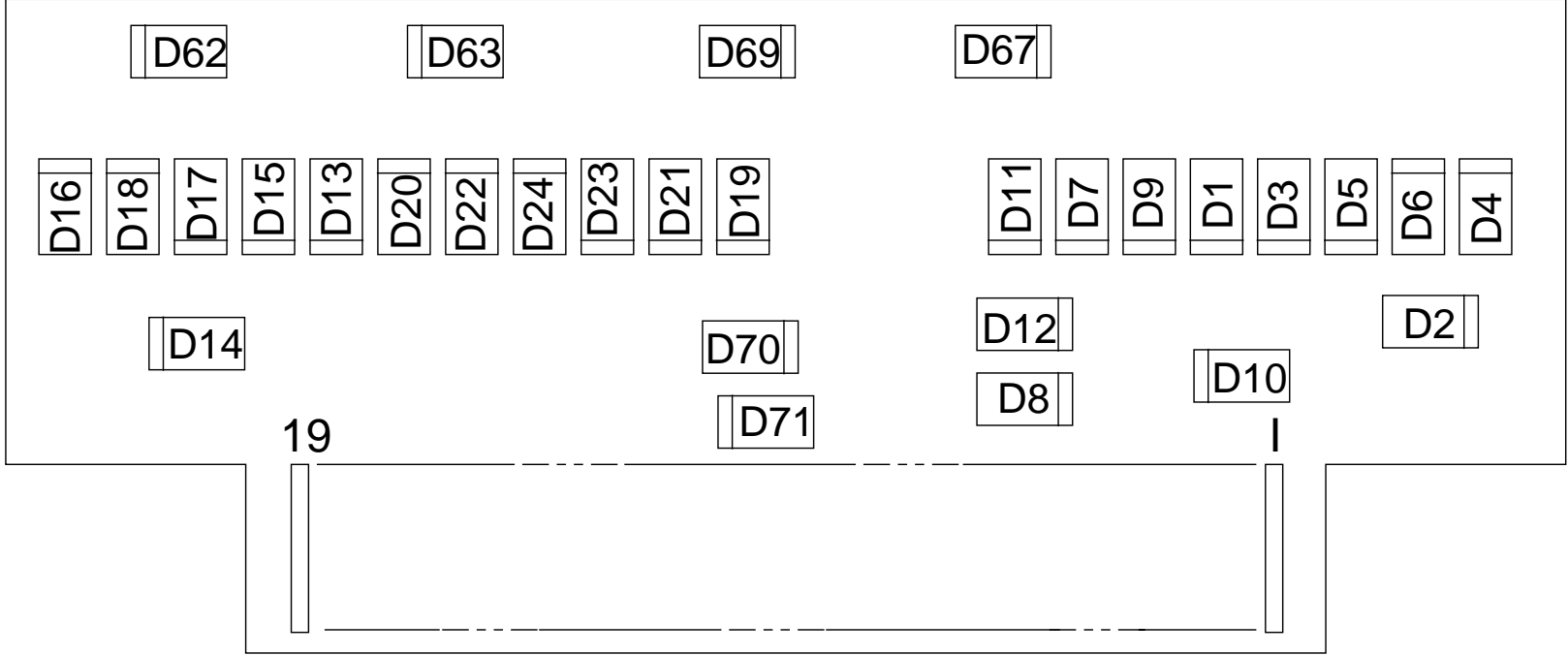
Figure 21. SDG-2T Component Location of Magnitude Comparator Board

# RELAY TYPE SDG-484T OUTPUT AND CHECK BOARD



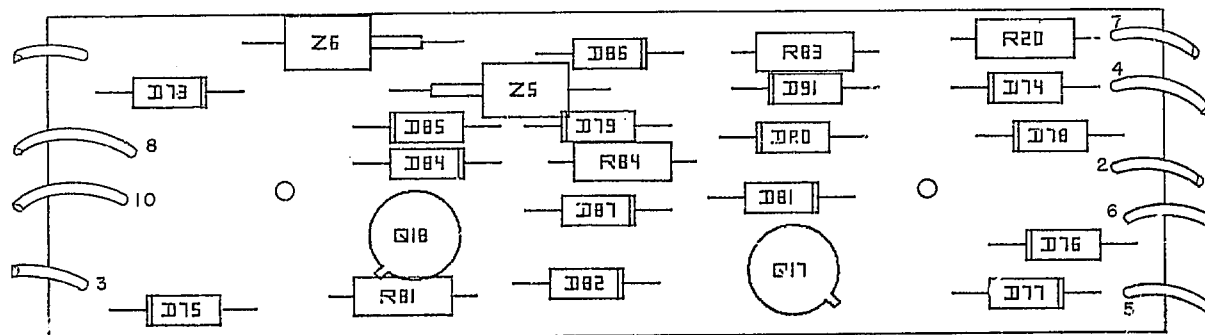
Sub 5  
203C301

Fig. 22. SDG-4T Component Location



Sub 1  
716B095

Figure 23. SDG-1T-2T-4T Component Location of Phase Splitter Rectifier Board



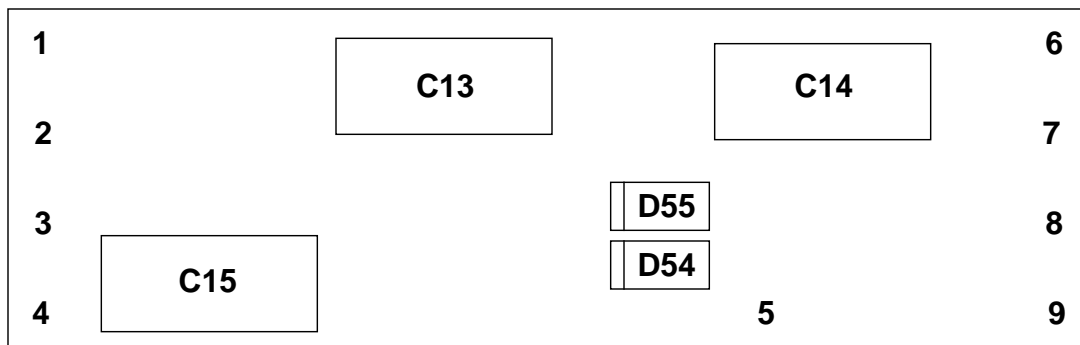
Ref. Dwg:

SYS. SCHEM. SDG-1T - 6694D74

SYS. SCHEM. SDG-2T - 6694D77

Sub 1  
774B966

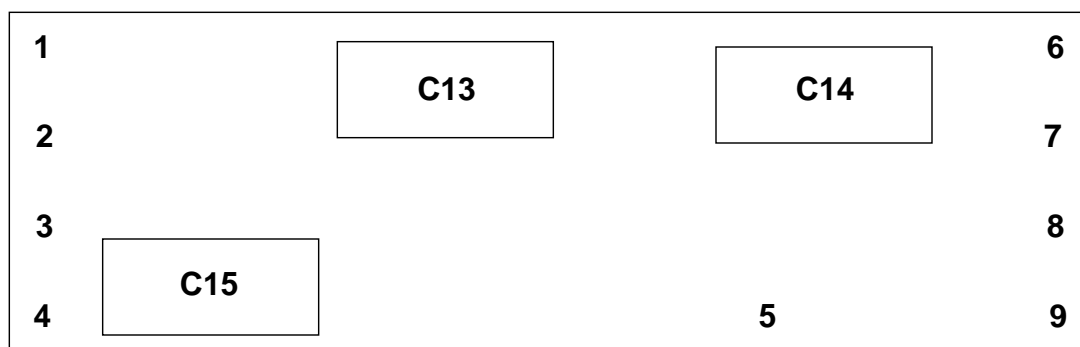
Figure 24. SDG-1T and SDG-2T 20-Ground Board Parts Location



**REF. DWG.  
CKT. BD. ASSY. 203C377G06  
SYS. SCHEM. 6694D74**

Sub 1  
3507A85

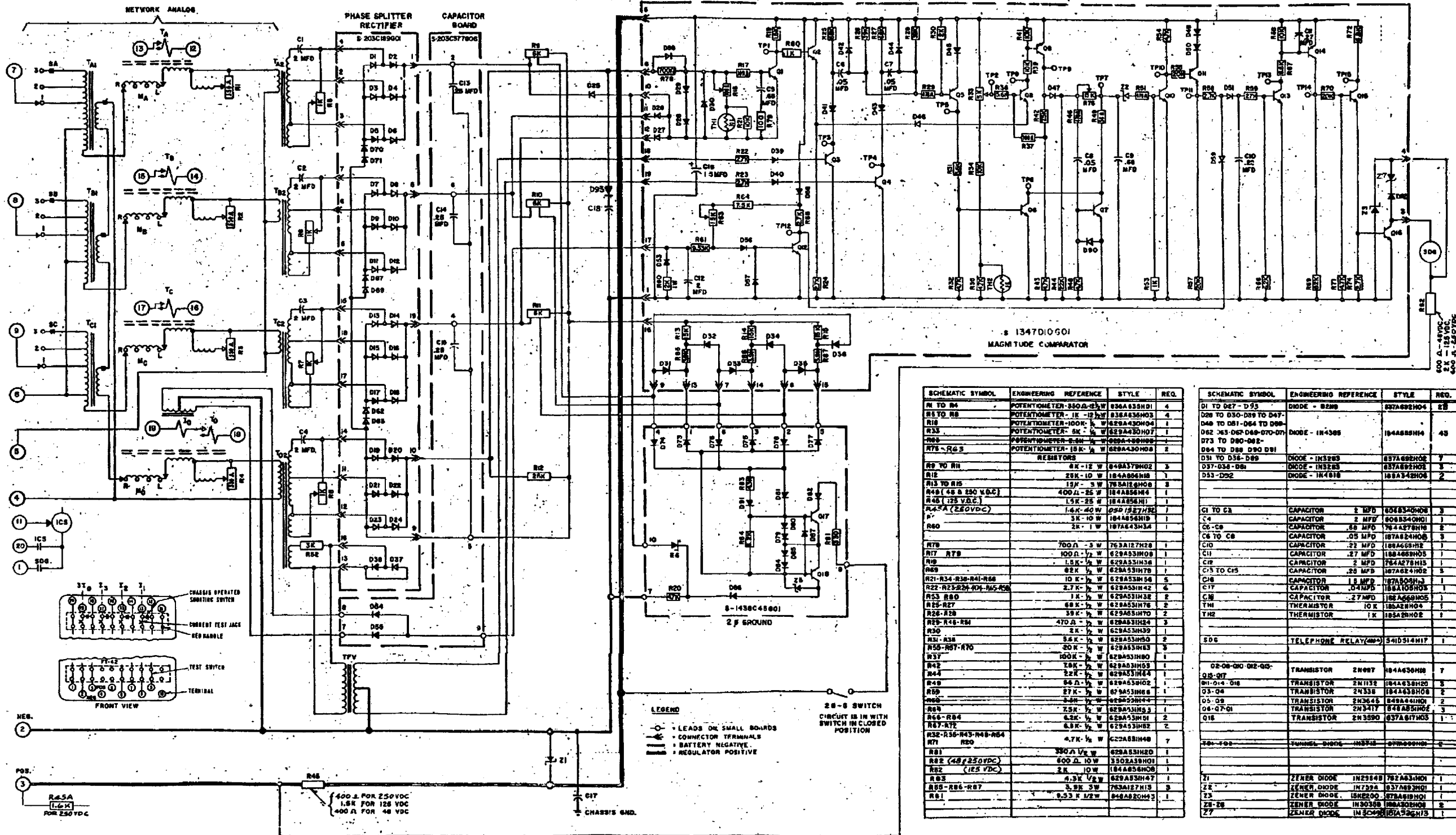
*Figure 25. SDG-1T Capacitor – Restraint Filter Board – Parts Location*



**REF. DWG.  
CKT. BD. ASSY. 203C377G07  
SYS. SCHEM. 6694D77**

Sub 1  
3507A86

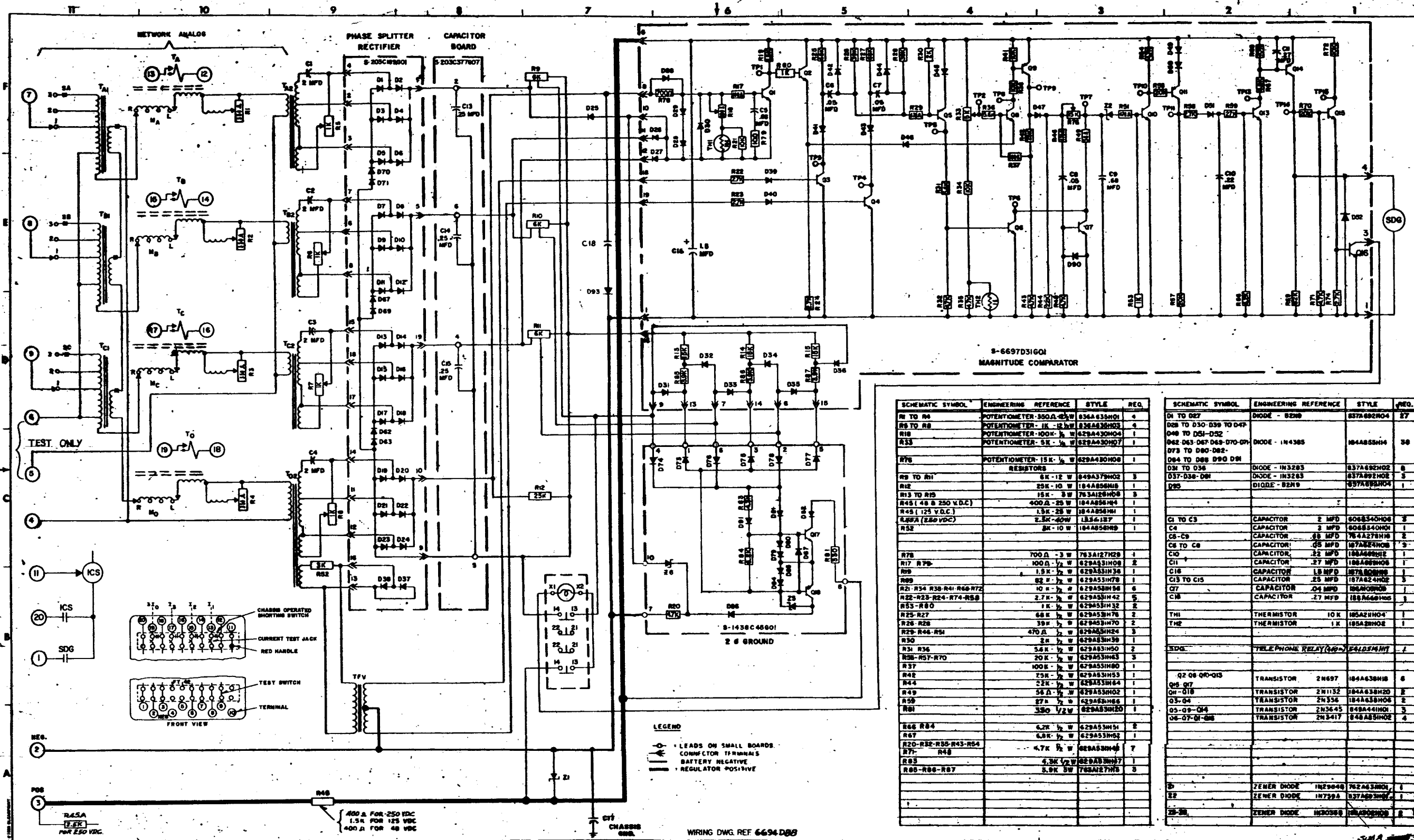
*Figure 26. SDG-2T Capacitor – Restraint Filter Board – Parts Location*



1347101001  
MAGNITUDE COMPARATOR

SCHEMATIC SYMBOL	ENGINEERING REFERENCE	STYLE	REQ.
R1 TO R4	POTENTIOMETER-350A-25W	836A353H01	4
R5 TO R8	POTENTIOMETER-1K-12W	836A353H02	4
R16	POTENTIOMETER-100K-1/2W	836A353H04	1
R33	POTENTIOMETER-5K-1/2W	836A353H07	1
R65	POTENTIOMETER-50K-1/2W	836A353H08	1
R75-R83	POTENTIOMETER-15K-1/2W	836A353H09	2
RESISTORS			
R9 TO R11	4K-12W	844A37H02	3
R12	25K-10W	844A37H03	1
R13 TO R15	15K-3W	844A37H04	3
R48 (48 250 W.D.C)	400A-25W	844A37H04	1
R49 (125 W.D.C)	1.5K-25W	844A37H01	1
R45A (250VDC)	1.4K-40W	844A37H02	1
R7	3K-10W	844A37H03	1
R80	2K-1W	844A37H04	1
R79	700A-3W	844A37H02	1
R17-R18	100A-1/2W	844A37H03	1
R19	1.5K-1/2W	844A37H04	1
R69	82K-1/2W	844A37H01	1
R21-R34-R36-R41-R66	10K-1/2W	844A37H02	5
R22-R23-R24-R4-R65-R68	2.7K-1/2W	844A37H03	6
R33-R37	2K-1/2W	844A37H04	2
R25-R27	68K-1/2W	844A37H01	2
R28-R29	33K-1/2W	844A37H02	2
R30-R46-RM	470A-1/2W	844A37H03	3
R31	2K-1/2W	844A37H04	1
R31-R38	56K-1/2W	844A37H01	2
R50-R57-R70	20K-1/2W	844A37H02	3
R57	100K-1/2W	844A37H03	1
R42	10K-1/2W	844A37H04	1
R43	22K-1/2W	844A37H01	1
R49	94A-1/2W	844A37H02	1
R59	27K-1/2W	844A37H03	1
R60	2.5K-1/2W	844A37H04	1
R64	25K-1/2W	844A37H01	1
R65-R68	6.2K-1/2W	844A37H02	2
R67-R72	6.8K-1/2W	844A37H03	2
R32-R35-R43-R48-R54	4.7K-1/2W	844A37H04	7
R71	300A-1/2W	844A37H01	1
R81	300A-1/2W	844A37H02	1
R82 (48 250VDC)	600A-10W	844A37H03	1
R82 (125 VDC)	2K-10W	844A37H04	1
R83	4.3K-1/2W	844A37H01	1
R85-R86-R87	3.9K-3W	844A37H02	3
R81	0.55K-1/2W	844A37H03	1

SCHEMATIC SYMBOL	ENGINEERING REFERENCE	STYLE	REQ.
D1 TO D27-D33	DIODE - 82M8	837A82H04	28
D28 TO D30-D39 TO D47-D49 TO D51-D64 TO D68-D62-D63-D67-D69-D70-D71	DIODE - 1N4368	184A85H04	43
D73 TO D80-D82	DIODE - 1N4368	184A85H04	8
D84 TO D88-D90-D91	DIODE - 1N4368	184A85H04	5
D91 TO D93-D99	DIODE - 1N4368	184A85H04	7
D37-D38-D91	DIODE - 1N4368	184A85H04	3
D53-D52	DIODE - 1N4368	184A85H04	2
C1 TO C3	CAPACITOR 2 MFD	8048340H02	3
C4	CAPACITOR 2 MFD	8048340H01	1
C5-C6	CAPACITOR .05 MFD	8048340H02	2
C6 TO C8	CAPACITOR .05 MFD	8048340H03	3
C10	CAPACITOR .22 MFD	8048340H04	1
C11	CAPACITOR .27 MFD	8048340H05	1
C12	CAPACITOR 2 MFD	8048340H06	1
C15 TO C18	CAPACITOR .25 MFD	8048340H07	4
C16	CAPACITOR 1.5 MFD	8048340H08	1
C17	CAPACITOR .04 MFD	8048340H09	1
C19	CAPACITOR .27 MFD	8048340H10	1
TM1	THERMISTOR 10K	185A28H04	1
TM2	THERMISTOR 1K	185A28H02	1
SDG	TELEPHONE RELAY (40V)	341D314H17	1
Q2-Q8-Q10-Q12-Q13-Q15-Q17	TRANSISTOR 2N987	184A43H02	7
Q1-Q14-Q16	TRANSISTOR 2N1132	184A43H03	3
Q3-Q9	TRANSISTOR 2N338	184A43H04	2
Q5-Q9	TRANSISTOR 2N364B	184A43H05	2
Q6-Q7-Q1	TRANSISTOR 2N3417	184A43H06	3
Q18	TRANSISTOR 2N3590	184A43H07	1
Z1 TO Z4	ZENER DIODE 1N2948	877A29H02	4
Z1	ZENER DIODE 1N2948	877A29H01	1
Z2	ZENER DIODE 1N759A	877A29H02	1
Z3	ZENER DIODE 1N2948	877A29H03	1
Z5-Z8	ZENER DIODE 1N3058	184A29H04	4
Z7	ZENER DIODE 1N3058	184A29H05	1



SCHEMATIC SYMBOL	ENGINEERING REFERENCE	STYLE	REQ.
R1 TO R4	POTENTIOMETER - 350A - 25W	636A-635H01	4
R5 TO R8	POTENTIOMETER - 1K - 12W	636A-635H02	4
R9	POTENTIOMETER - 100K - 1/2 W	629A-630H04	1
R33	POTENTIOMETER - 5K - 1/2 W	629A-630H07	1
R76	POTENTIOMETER - 15K - 1/2 W	629A-630H08	1
R9 TO R11	RESISTORS		
R12	5K - 12 W	649A-637H02	3
R13	25K - 10 W	184A-656H15	1
R14	15K - 3 W	763A-127H08	3
R45 (48 & 250 V.D.C.)	400A - 25 W	184A-656H14	1
R45 (125 V.D.C.)	1.5K - 25 W	184A-656H11	1
R57A (250 V.D.C.)	2.5K - 40W	183A-187	1
R52	5K - 10 W	184A-656H19	1
R78	700A - 3 W	763A-127H29	1
R17 R79	100A - 1/2 W	629A-631H08	2
R89	1.5K - 1/2 W	629A-631H36	1
R99	82 W - 1/2 W	629A-631H78	1
R21-R34 R38-R41-R68-R72	10 K - 1/2 W	629A-631H86	6
R22-R23-R24-R74-R58	2.7K - 1/2 W	629A-631H42	5
R53-R80	1K - 1/2 W	629A-631H32	2
R25-R27	68K - 1/2 W	629A-631H76	2
R26-R28	39K - 1/2 W	629A-631H70	2
R29-R46-R51	470A - 1/2 W	629A-631H24	3
R30	2K - 1/2 W	629A-631H39	1
R31-R36	5.6K - 1/2 W	629A-631H50	2
R36-R57-R70	20K - 1/2 W	629A-631H83	3
R37	100K - 1/2 W	629A-631H80	1
R42	75K - 1/2 W	629A-631H53	1
R44	22K - 1/2 W	629A-631H64	1
R49	56A - 1/2 W	629A-631H02	1
R59	87A - 1/2 W	629A-631H66	1
R61	350 1/2 W	629A-631H20	1
R66-R84	62K - 1/2 W	629A-631H51	2
R67	6.8K - 1/2 W	629A-631H82	1
R20-R32-R35-R43-R54	4.7K - 1/2 W	629A-631H44	7
R71-R48	4.7K - 1/2 W	629A-631H47	1
R83	5.9K 5W	763A-127H15	3
R60-R66-R67			

SCHEMATIC SYMBOL	ENGINEERING REFERENCE	STYLE	REQ.
D1 TO D27	DIODE - 62M8	637A-682H04	27
D28 TO D30 D39 TO D47	DIODE - IN4365	184A-655H14	36
D48 TO D51-D52	DIODE - IN4365	184A-655H14	36
D62-D63-D67-D69-D70-D71	DIODE - IN4365	184A-655H14	36
D73 TO D80-D82	DIODE - IN4365	184A-655H14	36
D84 TO D88 D90-D91	DIODE - IN4365	184A-655H14	36
D31 TO D36	DIODE - IN3283	637A-682H02	6
D37-D38-D39	DIODE - IN3283	637A-682H02	3
D95	DIODE - 62M8	637A-682H04	1
C1 TO C3	CAPACITOR		
C4	CAPACITOR		
C5-C9	CAPACITOR		
C6 TO C8	CAPACITOR		
C10	CAPACITOR		
C11	CAPACITOR		
C16	CAPACITOR		
C13 TO C15	CAPACITOR		
C17	CAPACITOR		
C18	CAPACITOR		
TH1	THERMISTOR		
TH2	THERMISTOR		
SDG	TELEPHONE RELAY (24V-75415M1)		
Q2-Q8-Q10-Q13	TRANSISTOR		
Q9-Q17	TRANSISTOR		
Q1-Q18	TRANSISTOR		
Q3-Q4	TRANSISTOR		
Q5-Q9-Q14	TRANSISTOR		
Q6-Q7-Q16	TRANSISTOR		
Z	ZENER DIODE		
Z2	ZENER DIODE		
Z3-Z8	ZENER DIODE		



